

# **Title: The Structure of Space and the Nature of Elementary Particles**

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## **Abstract:**

Can General Relativity and Quantum Mechanics emerge from a model where the Universe is represented as a four dimensional elastic media comprised of energy density and particles are travelling wave and standing wave solutions to a second order hyperbolic partial differential equation that provides shear wave, compression wave, and surface wave solutions to the differential equation that evolve in time? Quantum Mechanics and General Relativity are the two principle theories of modern physics and both work extremely well in its realm of use. However, the theories appear to be incompatible. String Theory and Quantum Loop Gravity have been proposed as means of unifying Quantum Mechanics and General Relativity, but neither has been successful at recreating the results of both theories or of providing new predictions. The model exactly reproduces the geodesic paths of General Relativity, explains how forces work, provides a framework for Quantum Mechanics, and makes useful predictions.

## The Structure of Space

In our normal day to day experience, we observe space-time to be comprised of three space dimensions and one time dimension. We also observe objects in space, where these objects comprise massless gauge bosons and massive particles. Additionally, every object in space is comprised of energy, where massive objects have both rest energy (also known as internal energy) and momentum energy (also known as kinetic energy).<sup>1,2</sup> Accordingly, each object in space has an energy density ' $P_E$ ' associated with that object for each point in space, where the energy density at each point  $X$  in space is approximately equal to the object's energy divided by the distance squared ' $/r(X)^2$ ' from the object to the point  $X$ . Additionally, the total energy density at a point in space is equal to the sum of the energy densities for all objects at that point in space and the energy density changes as a function of time depending upon how the distribution of energy changes as a function of time, where the magnitudes of energy, distance, and time are also dependent upon the observer's reference frame.

$$P_E(X, t) \approx E/r(X, t)^2. \quad (1).$$

$$P_{E(\text{tot})}(X, t) = \sum P_E(X, t) \quad (2).$$

Accordingly, each point of space has a total energy density associated with that point, where the total energy density can change as a function of time. We can consider energy density to provide a fourth space dimension such that space is considered to comprise a four dimensional shell with the three traditional space dimensions being the surface of the shell. It is likely, but not necessary, that the shell is the four dimensional analog to a sphere.

Therefore, we can consider space-time to be a four dimensional shell where the thickness of the shell varies with time based upon how the energy distribution in the Universe varies with time as viewed by the observer. Additionally, the solutions to the General Relativity equations require that the Universe is either expanding or contracting in time.<sup>1, 2</sup> Accordingly, the radius of the Universe will vary as a function of time depending upon how the Universe is expanding or contracting. The expansion of the Universe will decrease the energy density and the thickness of the shell for each point in space, while contraction of the Universe would increase the thickness of the shell.

The Universe is analogous to a four dimensional balloon, where the magnitude of energy density is equivalent to the thickness of the rubber of the balloon. The 4D elastic shell is the sum of the energy densities of all particles at that point.<sup>3, 4</sup> However, the four dimensional elastic shell of energy density does not have a reference frame, since it comprises energy density from everything.

The rate of time experienced by an object at a point in space can be thought of as corresponding to the rate of change of the radius of space at that point. Areas of the 3D surface of space having high energy density would expand or contract at a lower rate than areas of the surface having lower energy density areas because the thicker part of the shell would not expand or contract as quickly as thinner areas of the shell. It is equivalent to blowing up a balloon that has varying thicknesses of rubber.

An object observed to be traveling through a high density area of space will be observed to have a lower rate of time than an object traveling through a low energy density area of space.

Accordingly, the curved space-time described by the solutions to the General relativity equations can be seen to be a consequence of the difference in the magnitudes of energy density at different points in space that alter the rate of the expansion or contraction of space at that point. Hence, the magnitude of energy density at a location determines the relative extent to which an object is moving through time or space.

The metric tensor is a 4X4 matrix  $G$  that is used to determine distance in Special Relativity and General Relativity and that provides the inner product.<sup>2</sup> In Special Relativity, only the diagonal elements of the metric tensor are non-zero, where the diagonal elements are 1, 1, 1, 1 and where the first element is contravariant such that it provides a negative one in the inner product. However, in General Relativity, all 16 elements of the metric tensor can be non-zero, unless limiting restrictions are placed on the mass distribution or on the intensity of the gravity field.<sup>1-4</sup>

The value of the matrix elements of the metric tensor are determined by the energy density in the Universe in accordance with the appropriate solution to the equations of General Relativity.<sup>1-4</sup> For analysis purposes, simplified mass distributions are often used. In weak gravity fields, the metric tensor can be approximated by applying a metric tensor having non-zero elements only along the diagonal.<sup>3, 4</sup> Further, by representing each of the diagonal elements of the tensor as the infinite sum of analytic basis functions, you can diagonalize the matrix by reducing the matrix to a matrix that has only non-zero elements on the diagonal, which is done by applying the appropriate transforms.<sup>2</sup> For the remainder of this paper we will assume that the metric tensor has been diagonalized.

The  $G_{00}$  element of the General Relativity metric tensor is the element in the upper left hand corner of the matrix and it is contravariant such that it has a negative sign applied to it to provide the inner product. The  $G_{00}$  element of the metric tensor is a function of the energy density, where the  $G_{00}$  element equals 1 at a location infinitely far from a source of energy and where it has a value of zero at the surface of a black hole. The weak field approximation for the  $G_{00}$  element of the metric tensor is just the first two elements of the infinite sum that defines the  $G_{00}$  element for all cases, where the weak field approximation for a symmetric mass distribution is given by the following equation.

$$G_{00}(r) = 1 - 2GM/rc^2. \quad (3)$$

'G' is the gravitational constant; 'M' is the mass; 'r' is the distance from  $X_r$  to  $X_0$ ; and 'c' is the speed of light. The error of the approximation can be made as small as desired by adding additional terms to the infinite sum that equals the  $G_{00}$  element.

The other three diagonal elements of the metric tensor describe the asymmetry of metric and the corresponding inner products, where the asymmetry is caused by the asymmetry of the energy distribution in space. Accordingly, the  $G_{11}$ ,  $G_{22}$ , and  $G_{33}$  elements of the metric tensor correspond to the gradient of the energy density, where the  $G_{11}$  element corresponds to the x dimension, the  $G_{22}$  term corresponds to the y dimension, and the  $G_{33}$  term corresponds to the z dimension. If the energy density distribution is asymmetrical, the values of the elements  $G_{11}$ ,  $G_{22}$ , and  $G_{33}$  will each be different from 1. However, the sum of  $G_{11}$ ,  $G_{22}$ , and  $G_{33}$  will always be 3. <sup>3, 4</sup>

## **The Nature of Elementary Particles**

As explained above, space provides a four dimensional elastic medium. Three dimensional elastic mediums, such as the Earth's crust, are known to have compression waves (P waves), shear waves (S waves) and surface waves (Rayleigh waves and Love waves), where those waves are time dependent solutions to a second order hyperbolic partial differential equation.<sup>2, 5</sup>

Accordingly, similar waves should exist in the four dimensional elastic medium that comprises space. Indeed, elementary particles are travelling wave and standing wave solutions to a second order hyperbolic partial differential equation, which is the same differential equation that applies to seismic waves in the Earth.

Photons are shear waves that oscillate in two of the normal space dimensions and travel in the third space direction. The differential equations and the wave function solutions and the wave properties for a photon can be seen to be exactly the same as those of a shear wave in the Earth. An electron is shown to be a standing wave comprising two photons, where the standing wave of the electron affects the space surrounding the electron and causes some of that space to become anisotropic (having different velocities in different directions).<sup>2, 5</sup> The location of an electron is at its central wave packet, which is where a photon would most likely interact with the standing wave. All gauge bosons are traveling waves, like photons. All massive particles are standing waves or linear combinations of standing waves, like electrons. The standing waves provide the particles with a rest energy that corresponds to all of the energy of the particle (standing wave) when it is at rest. Kinetic energy (momentum energy) is additional energy that the particle has in addition to its rest energy and it causes the standing wave as measured from the observer's wave

to move with respect to the observer's standing wave and will correspond to the group velocity of the particle.

A group of seismic waves will split off a travelling wave, if the seismic wave encounters anisotropic. <sup>5</sup> Similarly, when a charged massive particle (standing wave) encounters anisotropic space, the anisotropic space of the charged particle interacts with the anisotropic space and splits off a photon. This occurs when two electrons interact and exchange photons (traveling waves).

Savickas and Hilo have separately demonstrated that the speed of light in a vacuum is proportional to the square root of the  $G_{00}$  element of the metric tensor. <sup>6, 7, 8</sup> Hilo generalizes the Special Relativity gamma factor such that it can be applied in the presence of gravity in accordance with General Relativity, where the generalized gamma factor is given by the following equation.

$$\gamma_{\text{SpecialGeneral}} = 1 / \sqrt{(G_{00} - (v^2/c^2))}. <sup>7, 8</sup> \quad (4)$$

Since the generalized gamma factor approaches infinity as  $v$  approaches  $\sqrt{(G_{00})}c$ , the speed of light in a vacuum must be proportional to  $\sqrt{(G_{00})}$ .

A gravity well is a volume of space where the total energy density increases as you approach the center of the volume. Accordingly, light will refract towards the normal in accordance with Snell's law when it travels into a gravity well, since the  $G_{00}$  element of the metric tensor gets smaller for greater mass density. <sup>2, 9</sup>

$$N = c/v = c/\sqrt{(G_{00})}c = 1/\sqrt{(G_{00})} \quad (5).^{2,6,7,8}$$

$$N_1 \sin(\theta_1) = N_2 \sin(\theta_2) \quad (6)^{2,9}$$

$$\theta_2 = \theta_1 (\text{inv} \sin(\sqrt{(G_{00}(X_2))} / \sqrt{(G_{00}(X_1))})). \quad (7)^{2,6,7,8,9}$$

‘N’ is the index of refraction in a vacuum; ‘c’ is the speed of light in Minkowski space at the rate of time in Minkowski space, where the speed of light will always be measured at c for light traveling in the same  $G_{00}$  level as the observer; ‘ $\theta$ ’ is the angle with respect to the normal, where the normal is provided by the gradient of energy density; ‘X’ is the location of the object on the 3D surface of space at the appropriate time.

The refraction of a standing wave is determined by the refraction of travelling waves it is comprised of, since the phase velocity of the standing waves is determined is the speed of traveling waves of which they are comprised (the speed light).<sup>2</sup> Accordingly, all massive objects will refract at exactly the same angle  $\theta$ ’ as light for the same location in space-time in accordance with equation 7. The direction of the normal to which the angle  $\theta$  is referenced is determined by the G11 element, the G22 element, and the G33 element of the metric tensor, since they represent the gradient of energy density. In a typical gravity well, the normal is parallel to the radius of the well and perpendicular to the surface.

Although the phase velocity of massive objects decreases as the gauge boson velocity decrease as the objects go deeper into a gravity well, the group velocity of massive objects (standing waves) typically increases as the particles go deeper into a gravity well. When a massive particle



goes deeper into a gravity well (an area of high energy density), the particle's rest energy decreases proportional to the decrease in  $\sqrt{G_{00}}$ , which means that the particle needs less energy to exist as a standing wave when it is deeper in the gravity well than when it is higher up in the gravity well.<sup>3, 4</sup> The kinetic energy of the massive object must increase by the amount that the rest energy decreases as the massive object goes deeper into the gravity well to conserve energy as observed from any specific reference frame.<sup>3, 4</sup> Accordingly, the velocity of the massive object must increase proportional to the change in the  $G_{00}$ . However, photons will get slower when they go deeper into a gravity well, since the  $G_{00}$  element of the metric tensor gets closer to zero.<sup>7, 9</sup> Accordingly, the gamma factor will eventually cause the speed of massive particles to decrease as they get deeper in a gravity well, since the standing wave velocity can never exceed the travelling wave velocity

Gravity is provided by the refraction of the standing waves and traveling waves, since refraction changes the direction of both the traveling waves and the standing waves in the same way, since the change in the  $G_{00}$  element, and since the  $G_{11}$  element, the  $G_{22}$  element, and the  $G_{33}$  element of the metric determine the normal. However, the  $\sqrt{G_{00}}$  does not provide an index of refraction in a vacuum that has sharp edges like the typical boundary between transparent condensed matter. Accordingly, gravity is provided by a gradually reducing index of refraction, since  $G_{00}$  is a continuous function. However, Maxwell has shown that a gradually reducing index of refraction can provide circular or elliptical orbits.<sup>9</sup> Accordingly, the refraction of all objects in a vacuum provides gravity identical to traditional General Relativity, since the paths of the particles are determined by all of the information contained in the metric tensor that represents the specific solution to the General Relativity equations for the applicable mass

distribution in time. Since both the refraction path and traditional GR geodesic path are provided by the identical information using the same solution to the General Relativity equations, both paths must be identical.

Standing waves made of compression traveling waves or shear traveling waves can reproduce all of the observable characteristics of massive elementary particles, such as spin and charge and quantum behavior. Gluons and photons are traveling shear waves, while quarks and electrons are standing waves made of two traveling shear waves. A photon involves oscillation between two space dimensions that correspond to the B and E fields, while all versions of quarks and gluons involves oscillation in a space dimension and the energy density dimension, including the quarks that make protons and neutrons.

Charged particles are standing waves that affect the distribution of energy density in space and which cause space to have different velocity in different directions, where space having different velocities in different directions is known as “anisotropic space.” Forces are a consequence of wave splitting or wave combining in anisotropic space, which is a phenomenon observed in 3D seismic waves.<sup>5</sup> The anisotropic space caused by two charged separate charged particles causes the charged particles to exchange photons when the anisotropic space caused by two distinct charged particles (charged standing waves) intersects.

Neutrinos are compression waves and can have velocities greater than C, since compression waves always travel faster than shear waves in elastic media.<sup>5</sup> In the 3D elastic medium of the of the Earth, the travelling P waves travel about 1.7 times faster than the travelling S waves, where

the 1.7 ratio applies for all media.<sup>5</sup> However, the velocity of neutrino gauge bosons is also proportional to  $G_{00}$  element of the metric tensor. Accordingly, the refraction of neutrinos and neutrino gauge bosons will be the same as the refraction of photons and electrons, which is provided by Snell's law as shown in equations 5-7.

Anti-matter is a massive particle having a traveling wave component 180 degree out of phase with a traveling wave component of the corresponding matter particle, such that the combination of the two standing waves' out of phase component travelling waves would free the remaining traveling wave from each particle after the two out of phase traveling waves cancelled each other out.

## **Discussion**

The observed characteristics of elementary particles can all be represented by the characteristics of travelling waves or of standing waves. Indeed, we know that photon waves can have spin and angular momentum and the additional degrees of freedom provided by shear and compression waves can represent all known elementary particle characteristics, where some of the more exotic particles could correspond to surface waves and their linear combination with shear and compression waves.<sup>2, 6, 7</sup> Energy between compression waves and shear waves and Surface waves can couple amongst them as determined by the differential equations, but the combinations are not always stable.<sup>5</sup> Further, we can expect energy density waves to have quantum behavior because they exist as eigenvectors (Eigen wave functions) of the system and thus only have specific quanta of value and because the uncertainty relation will naturally hold and because the travelling and standing waves are objects that extend through space.<sup>2,6</sup>

Accordingly, the probabilities of interactions of a photon with a massive particle will obey the statistical probabilities of Quantum Mechanics or Quantum Field theory.

In elastic media, a wave will split into two waves when it encounters anisotropic media, where anisotropic media is media where the wave velocity varies according to direction.<sup>5</sup> Anisotropic media can also provide wave combining.<sup>5</sup> Charged particles (charged standing waves) create anisotropic space, unless they are balanced out by an equal but opposite charge. Accordingly, neutral particles do not have anisotropic space except in the close vicinity of the charged particle. When the anisotropic space of two standing waves intersect, both standing waves emit traveling waves (i.e. photons or gluons) that are absorbed by the other standing wave. However, such photons likely couple directly from one particle (standing wave) to the other so that no free standing photon ever exists when a force is applied by a charge. When a photon interacts with the anisotropic space near a particle, the velocity difference between the particle's component travelling wave and the incident travelling wave cause the waves to combine.

Although the four dimensional shell that comprises space does not have a reference frame, frame dragging will be caused if a large mass, such as a black hole, is rotating, since the energy of the large mass over its radius squared will dominate the energy density in its local area. This frame dragging imposes a rotation into the local elastic shell near the large rotating mass. The rotation of the frame will likely cause a close orbiting star to acquire large additional velocity and kinetic energy as it goes through the frame dragging area. The relative amount of rotation of space (the energy density shell) will increase as you approach the boundary of the black hole and the rotation of the energy density shell will provide velocity and energy to the star (standing

wave) in a manner similar to what would happen to a sound wave travelling through an ocean current.

When a massive particle (standing wave) is moved upwards in a gravity well, the rest energy and physical size of the standing wave varies in exactly the same way that is predicted for general relativity.<sup>3</sup> The increase in rest energy is represented by a greater peak to peak value of the standing wave and by a greater frequency of the component traveling waves and the decrease in physical size or radius is represented by a wave packet that is more tightly bound and has a shorter wavelength. However, the photon energy does not change when the photon moves up in the gravity well. Accordingly, Lev Okun's statement "the phenomenon known as the red shift of a photon is the blue shift of an atom" applies to the standing wave solutions (atoms) and travelling wave solutions (photons) moving up in a gravity well.<sup>3, 4</sup>

Space is shown to exist as a four dimension elastic shell of energy density comprised of the energy densities of each object in the Universe. Elementary particles are travelling wave and standing wave solutions to a second order hyperbolic partial differential equation for a four dimensional elastic medium. This partial differential equation is the same equation as the partial differential equation for seismic waves in the Earth, except that it includes an additional dimension. Forces are created by anisotropic space, which causes a standing wave to emit travelling waves and to absorb travelling waves. General Relativity and Quantum mechanics emerge from this model. Gluons and photons are traveling shear waves, while quarks and electrons are standing waves made of two traveling shear waves and which also include a standing compression wave (neutrino). W bosons are traveling surface waves and Z bosons are

standing waves comprised of W bosons. Gravity is a type of refraction, where the velocity of a traveling wave is proportional to the  $\sqrt{G_{00}}$  element of the metric tensor, where the angle of an object with respect to the normal of a gravity well will be given by equation 7.

## References and Notes:

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