

# Numerical calculation of the Rainich space in the vicinity of a singularity

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**Abstract:** The well known numerical method of approximating differential quotients by quotients of differences is used in a novel context. This method is commonly underestimated, wrongly. The method is explained by an ordinary differential equation first. Then it is demonstrated how this simple method proves successful for non-linear field equations with chaotic behaviour. Using certain discrete values of their integration constants, a behaviour comparable with MANDELBROT sets is obtained. Instead of solving the differential equations directly, their convergence behaviour is analyzed. As an example the EINSTEIN-MAXWELL equations are investigated, where discrete particle quantities are obtained from a continuous theory, which is possible only by this method. The special set of integration constants contains values identical with particle characteristics. Known particle values are confirmed, and unknown values can be predicted. In this paper, supposed neutrino masses are presented.

**Keywords:** Riemannian geometry, Theory of relativity, Rainich theory, Singularities, Numerical simulations, Algorithm, Chaos

## 1 Introduction

In preceding work of RAINICH [1, 2] and, later, BRUCHHOLZ [3, 4] the geometry of electromagnetism has been determined by unifying electrodynamics with EINSTEIN's theory of general relativity [5]. The RICCI tensor [6] is constructed from the electromagnetic field in tensor representation. This geometry is conterminous with the geometry of the V4 of signature 2 in general. The singularity problem arising from the equations of this geometry is

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solved geometrically. The geometric equations are formulated numerically, i.e. as difference equations. The integration constants are parameters in corresponding recursion formulae, and take on discrete values. Variation of the parameters leads to a characteristic convergence behaviour of the numerical equations. There are points in the parameter space leading to minimal divergence that are taken as their physically relevant values. – The physical significance of these insights and results is obvious.

In section 2, the theory of the unified field is explained. In the third section, the numerical method is described. This is applied in sections 5 and 6 with the parameters determined in section 4. The algorithms are discussed in the sixth section, and some computational results are given in section 7, in particular for the neutrino masses which have not been determined by any other theoretical method to date. Section 8 draws some conclusions.

## 2 The equations

The theory is based on the relativistic tensor equations [3] of RIEMANNIAN (non-EUCLIDEAN) geometry (quoted from [7]):

$$R_{ik} = \kappa \left( \frac{1}{4} g_{ik} F_{ab} F^{ab} - F_{ia} F_k{}^a \right) \quad , \quad (1)$$

$$F_{ij,k} + F_{jk,i} + F_{ki,j} = 0 \quad , \quad (2)$$

$$F^{ia}{}_{;a} = 0 \quad , \quad (3)$$

in which  $g_{ik}$  are the components of metrics,  $R_{ik}$  those of the RICCI tensor and  $F_{ik}$  those of the electromagnetic field tensor.  $\kappa$  is EINSTEIN's gravitation constant. The partial derivative is denoted by a comma, the covariant derivative by a semicolon. If we express the field tensor by a vector potential  $\mathbf{A}$  with

$$F_{ik} = A_{i,k} - A_{k,i} \quad , \quad (4)$$

equation (2) is identically fulfilled. Thus, we can base the calculations on quantities having the character of potentials that are metrics and the electromagnetic vector potential.

These equations are known as EINSTEIN-MAXWELL equations. The energy-momentum tensor of electrodynamics is equated to the energy-momentum tensor of EINSTEIN's theory [5]. In detail, the *homogeneous* MAXWELL equations are used. Only these fulfill force equilibrium and

conservation of energy and momentum (mathematically expressed by the BIANCHI identities, see also appendix). These equations describe physically the electrovacuum around a particle and involve geometry described by the EINSTEIN part (equation (1)) of the equations. It is the geometry of the V4 of signature 2, also called space-time, as long as we do not consider constant curvature (see [6]), which is linearly superimposed with the fields.

These equations and the involved geometry were found by RAINICH already in the year 1924 [1, 2]. Therefore, we will call the space-time RAINICH space. BRUCHHOLZ [3] derived this geometry independently of RAINICH in a different way traced out by EISENHART [6], with the same result.

The geometric equations yield only 10 independent equations for 14 components  $g_{ik}, A_i$ , what means that the geometry respectively the field is not completely determined. As well, it will be demonstrated that the omnipresent quantization in physics has nothing to do with this indeterminacy. The quantization is the consequence from chaotic behaviour of the geometric equations, even also if we override the indeterminacy with additional conditions.

### 3 Explanation of the numerical method

For completeness of arguments we repeat in this section what was already worked out in [7].

In direct numerical solutions of differential equations the differential quotient is replaced by a quotient of finite differences. This leads to recursion rules on the calculational grid. In the following we will derive a scheme of differences which is suitable for the type of problems we will solve in section 6. We consider a differential equation of the form

$$f''(x, c_\nu) + F(x, f'(x), c_\nu) = 0 \quad (5)$$

where  $F$  is a function of the derivative of the function  $f(x)$  to be found.  $F$  and  $f$  depend on a set of constants  $c_\nu$ . With difference quotients

$$\left. \frac{\partial f}{\partial x} \right|_{x_n} = \frac{f_{n+1} - f_{n-1}}{2 \Delta x} \quad (6)$$

and for the second derivative

$$\left. \frac{\partial^2 f}{\partial x^2} \right|_{x_n} = \frac{f_{n+2} - 2f_n + f_{n-2}}{(2 \Delta x)^2} \quad (7)$$

we obtain a recursion formula for the discrete function value of  $f$  at  $x_{n+2}$ :

$$f_{n+2} = 2f_n - f_{n-2} - (2 \Delta x)^2 F_n(c_\nu) \quad (8)$$

or, rewritten,

$$f(x + 2 \Delta x) = 2f(x) - f(x - 2 \Delta x) - (2 \Delta x)^2 F(x - \Delta x, x, x + \Delta x, c_\nu) . \quad (9)$$

We have chosen a difference of two grid points for the second derivative in order to obtain a simple recursion formula. The parameters  $c_\nu$  denote the integration constants of the differential equations and are part of the initial conditions. The latter are obtained from appropriate approximations of  $f$  in the initial range of  $x$ . For real-valued  $x$  and  $c_\nu$ , this iteration formula is able to behave in a chaotic manner, in dependence of the parameters  $c_\nu$ . These results can be generalized for systems of partial differential equations with many variables. In definition regions where the functions have diverging solutions, we obtain a map of the “degree of divergence” which can be graphed in a plane if we have two parameters  $c_1$  and  $c_2$  for example. All this is in analogy to the well known MANDELBROT sets familiar from chaos theory [8, 9].

We shall see from the EINSTEIN-MAXWELL equations that different values of the integration constants (as parameters) lead to a varying divergence behaviour. While  $f$  immediately diverges in most cases, there are discrete values of the parameters  $c$  where  $f$  diverges at a relatively sharply defined  $x$  value which stands for the radius here. (Further details are given in section 6.) These special values of the parameters perform a special set leading to a kind of “semi-stable” solutions of  $f$ . – In practice, this behaviour will be smeared over due to rounding errors. (Otherwise, we would not find the relevant discrete values.)

## 4 Determination of the parameters

Differential equations of the discussed type result with first approximation in wave equations

$$\square f = 0 \quad . \quad (10)$$

The integration constants from the wave equations are the parameters of the corresponding recursion formulae, named in section 3. It is detailedly explained in [4] how to compare the wave equations with corresponding

POISSON equations, which have an additional source term. The integration constants of the wave equations then replace the sources of the POISSON equations. Concrete terms for the EINSTEIN-MAXWELL equations can be seen in section 6.

## 5 The singularity problem and its solution

According to a theorem of EINSTEIN and PAULI [10], analytic solutions of equations (1,3,4) lead commonly to singularities. There are two types of singularities. The first type is a singularity inferred by assuming for example point masses and point charges in order to simplify the equations so that analytical solutions are feasible. This is often considered as a deficit when comparing a calculation with the situation in reality. However, in our calculations, these formal singularities are placed into the inner of the particle (according to observer's coordinates) which is not subject of calculation. The reason is as follows:

The observer uses coordinates in a tangent (asymptotic) space around the particle (with the singularity). The coordinates of the observer are projected onto the RAINICH space around the particle. We have a physically irrelevant region where this projection is not possible. The physically irrelevant regions are "behind" a geometric limit, which is the limit for this projection. Geometric limit means, at least one physical metrical component (explained in section 6) takes on an absolute value of 1. With spherical coordinates, the formal singularity is at the centre.

The basic idea of calculation is as follows. The equations (1,3,4) are evaluated on a radial grid from outer to inner and so one approaches the unknown inner area successively. At a certain radius, the calculation starts to diverge because the central singularity becomes predominant. It is important to notice that this radius of divergence is clearly separated from the central singularity so a second type of singularity here appears. ECKARDT called the second type a "numerical singularity" [7]. SCHMUTZER told that the (formal) singularity is displaced due to the chaos in the recursion formulae<sup>3</sup>. However, also the numerical singularity is always "behind" the geometric limit and, therefore, in the physically irrelevant region. – So neither the numerical singularity nor the formal singularity are a problem for geometric equations. The geometric limit will be revealed to be a boundary at the

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conjectural particle radius with numerical simulations according to the EINSTEIN-MAXWELL equations.

The geometric limit is the mathematical reason for the existence of discrete “semi-stable” (explained in section 3) solutions. Here a mix from chaos (see [4] and previous sections) and marginal-problems is acting. – These discrete solutions involve discrete values of the integration constants, which are also called eigenvalues in context with the marginal-problems. We shall see that the RAINICH space is able to produce such eigenvalues, and that the eigenvalues represent a set identical with the entirety of the particle characteristics.

## 6 Numerical simulations

In order to gain eigenvalues, one has to do lots of tests, because the particle quantities are integration constants and have to be inserted into the initial conditions (for more details see [4]), which are defined for the electrovacuum around the particle.

As already mentioned, the basis for computations are equations (1,3,4). For the sake of simplicity, we restrict equations (1,3,4) to time independence and rotational symmetry. That results, with spherical coordinates

$$x^1 = r , \quad x^2 = \vartheta , \quad x^3 = \varphi , \quad x^4 = jct ,$$

in 6 independent equations for 8 components with character of a potential,  $A_3, A_4, g_{11}, g_{12}, g_{22}, g_{33}, g_{34}, g_{44}$ , the other vanish. In order to override the indeterminacy by the two missing equations, we define

$$g_{12} = 0 \quad (\text{and, consequently, } g^{12} = 0) \quad (11)$$

and

$$g = \det|g_{ik}| = r^4 \sin^2 \vartheta \quad . \quad (12)$$

These conditions are arbitrary, in which the second is taken from the free-field MINKOWSKI metric. They are in combination leading to reasonable results. Important to notice: The integration constants do not change with arbitrary conditions like equations (11), (12).

The integration constants from equations (1,3,4) result from a series expansion. The first coefficients of expansion are the input for the simulations and are inserted into the initial conditions [4]. The output is the number of

grid points along the radius until divergence occurs, which is a measure for the stability of the solution.

The first coefficients (integration constants) are

$$c_1 = - \frac{\kappa m}{4\pi} \implies \frac{\kappa m}{4\pi} \quad (13)$$

(mass),

$$c_2 = j \frac{\kappa s}{4\pi c} \implies \frac{\kappa s}{4\pi c} \quad (14)$$

(spin),

$$c_3 = -j \frac{\mu_o^{\frac{1}{2}} Q}{4\pi} \implies \frac{\kappa^{\frac{1}{2}} \mu_o^{\frac{1}{2}} Q}{4\pi} \quad (15)$$

(charge), and

$$c_4 = - \frac{\varepsilon_o^{\frac{1}{2}} M}{4\pi} \implies \frac{\kappa^{\frac{1}{2}} \varepsilon_o^{\frac{1}{2}} M}{4\pi} \quad (16)$$

(magnetic moment).

As explained, these follow from a comparison of series expansion from the EINSTEIN-MAXWELL equations (homogeneous MAXWELL equations) with the solutions of corresponding inhomogeneous equations, see [4]. The dimensionless terms after the arrow are taken for computation, and have positive values. The imaginary unit has been eliminated. The unit radius ( $r = 1$ ) corresponds to  $10^{-15}$ m. By this, the initial conditions become, using  $T = \frac{\pi}{2} - \vartheta$ ,

$$g_{11} = 1 + \frac{c_1}{r} - \frac{1}{2} \left(\frac{c_3}{r}\right)^2 + \frac{\left(\frac{c_4}{r^2}\right)^2 (1 + \cos^2 T)}{10}, \quad (17)$$

$$g_{22} = r^2 \left\{ 1 + \left(\frac{c_4}{r^2}\right)^2 \left(\frac{1}{3} \cos^2 T - \frac{3}{10}\right) \right\}, \quad (18)$$

$$g_{33} = r^2 \cos^2 T \left\{ 1 + \left(\frac{c_4}{r^2}\right)^2 \left(\frac{\cos^2 T}{15} - \frac{3}{10}\right) \right\}, \quad (19)$$

$$g_{44} = 1 - \frac{c_1}{r} + \frac{1}{2} \left\{ \left(\frac{c_3}{r}\right)^2 + \left(\frac{c_4}{r^2}\right)^2 \sin^2 T \right\}, \quad (20)$$

$$g_{34} = r \cos^2 T \left( \frac{c_2}{r^2} - \frac{1}{2} \frac{c_3 c_4}{r^3} \right), \quad (21)$$

$$A_3 = r \cos^2 T \frac{c_4}{r^2}, \quad (22)$$

$$A_4 = \frac{c_3}{r}. \quad (23)$$

The physically relevant parts of the metrical components are called physical metric components. These are the complement to unity in equations (17-20). Denoting the complements by  $g_{(11)}$  etc. the above equations read

$$g_{11} = 1 + g_{(11)} , \quad (24)$$

$$g_{22} = r^2 (1 + g_{(22)}) , \quad (25)$$

$$g_{33} = r^2 \sin^2 \vartheta (1 + g_{(33)}) , \quad (26)$$

$$g_{44} = 1 + g_{(44)} . \quad (27)$$

The physical metric components have a magnitude of ca  $10^{-40}$  or smaller at the unit radius. Since several components contain unities, the physical components would have no effect due to lack of numerical precision during computation. Therefore, the actual computation is done with quantities performed from these physical components, with the consequence that the unity summands in the equations are eliminated.

We have to insert the values of the integration constants into the modified initial conditions (with physical components), see program in the data package (available at the author's website<sup>4</sup>). The conversion of physical into normalized (dimensionless) values and vice versa is described in detail in [4]. Table 1 shows some values with radius unit of  $10^{-15}$ m. These examples allow for convenient conversion.

	physical value	norm. value
proton mass	$1.672 \times 10^{-24}$ g	$2.48 \times 10^{-39}$
electr. mass	$0.911 \times 10^{-27}$ g	$1.35 \times 10^{-42}$
$\hbar$	$1.054 \times 10^{-27}$ cm <sup>2</sup> g/s	$5.20 \times 10^{-40}$
elem. charge	$1.602 \times 10^{-19}$ As	$1.95 \times 10^{-21}$
$\mu_B$	$1.165 \times 10^{-27}$ Vs cm	$3.70 \times 10^{-19}$

Table 1: Physical and normalized values for conversion

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<sup>4</sup>[http://www.bruchholz-acoustics.de/physics/neutrino\\_data.tar.gz](http://www.bruchholz-acoustics.de/physics/neutrino_data.tar.gz)

Higher moments are missing in the equations because of lack of knowledge, their influence is estimated to be rather small. In the results section we will insert known values and values deviating from them, and compare the results.

The algorithm for evaluating the equations requires numerical differentiation. We do this by separating the quantity with highest radius index at the left-hand side as described in section 3. All previously evaluated quantities are at the right-hand side. These quantities come from equations (1) and (3) using (4). For example when we calculate spherical shells from outside to inside, the new quantity is  $f_{m+2,n}$ . In the following difference equations  $f$  stands for *any* potential-like quantity:

$$\left. \frac{\partial f}{\partial r} \right|_{r_m, T_n} = \frac{f_{m-1,n} - f_{m+1,n}}{2 \Delta r}, \quad (28)$$

$$\left. \frac{\partial^2 f}{\partial r^2} \right|_{r_m, T_n} = \frac{f_{m+2,n} - 2f_{m,n} + f_{m-2,n}}{(2 \Delta r)^2}, \quad (29)$$

$$\left. \frac{\partial f}{\partial T} \right|_{r_m, T_n} = \frac{f_{m,n+1} - f_{m,n-1}}{2 \Delta T}, \quad (30)$$

$$\left. \frac{\partial^2 f}{\partial T^2} \right|_{r_m, T_n} = \frac{f_{m,n+1} - 2f_{m,n} + f_{m,n-1}}{\Delta T^2}. \quad (31)$$

From equation (29), and secondarily from equations (28), (30), (31), we obtain recursion formulae of the kind

$$f_{m+2,n} = 2f_{m,n} - f_{m-2,n} - (2 \Delta r)^2 F_{m,n}(c_\nu), \quad (32)$$

see also section 3. The  $F_{m,n}$  are very complex, and contain the non-linearities of the EINSTEIN-MAXWELL equations. Detailed formulae are available in the Pascal code (see author's web site above). This method is made possible by the fact that 2nd derivatives in the tensor equations appear always linearly. Therefore the doubled difference in equation (29) was introduced.

When the program runs, the values of the several components are successively quantified in one spherical shell after the other. The computation is done for all components along the inclination ( $\vartheta$  values) at a given radius, and along the radius (with all inclination values) from outside to inside step by step until geometric limits are reached. After starting the procedure, we get the values as expected from the initial conditions. Suddenly, the values grow over all limits. At this point geometric limits are reached and the calculation is stopped.

The step count (number of iterations) up to the first geometric limit of a metrical component (where the absolute value of the “physical” component becomes unity) depends on the inserted values of the integration constants. A relatively coarse grid reflects strong dependencies, however, the referring values of the integration constants are imprecise. Computations with finer grid lead to smaller contrast of the step counts, but the values are more precise.

The resulting eigenvalues of the integration constants are obtained where the step count until divergence is at maximum. Round-off errors have to be respected because these can be in the order of step count differences for the formulae.

In order to see the eigenvalues, lots of tests were run with parameters more and less deviating from reference values. The output parameter (used for the plots discussed in the results section) is the mentioned step count. In order to make visible the differences, the step count above a “threshold” is depicted in resulting figures by a more or less fat “point”.

Though neutrinos are uncharged, one has to use always the full EINSTEIN-MAXWELL equations (with zero charge and magnetic moments) to account for the inherent non-linearity. Because the information is in the entire field outside the geometric boundary, one has to do so even if charge and magnetic moment are zero. Higher moments exist anyway and are included in the calculation. Only in the (outer) initial conditions (when starting the calculations) they are neglected.

## 7 Computational results

### 7.1 Spins, electric charges, magnetic moments

Tests including parameters different from mass had to be run with an initial radius close to the conjectural particle radius. Here, the influences of the four relevant parameters onto the metric (about  $10^{-40}$ ) are comparable.

The best result has been achieved with the free electron, see [4]. The magnetic moment of the electron arises specially sharply, due to the dominant influence.

Unfortunately, the mass gets lost in the “noise” from rounding errors. Only cases with charge and mass together can be made visible in exceptional cases, see for example [4, 11].

## 7.2 Masses

### *Masses of nuclei*

The influence of mass on metrics prevails in a certain distance from the conjectural particle or nucleus radius, respectively. It proves being possible to set the remaining parameters to zero. Figs. 1 and 2 show related tests, with possible assignment of maxima in the figures to nuclei [11].

It was necessary in the tests according to Figs. 1, 2 to “pile up” the data. For this purpose, several test series with *slightly* different parameters (mostly initial radius) have been run, and the related step counts (the output) have been added. So the “noise” from rounding errors is successively suppressed. With 80 bit floating point registers, the rounding error is in the 20th decimal. As well, the relative deviation of difference quotients from related differential quotients *in the first step* is roughly  $10^{-20}$  – that is the limit, where the onset of chaotic behaviour can be seen. Consequently, simulations with only 64 bit (double) lead to no meaningful results.

One can see certain patterns in the figures, which could arise from errors by neglecting other parameters.

### *Masses of leptons*

It is principally possible to deduce the masses of all free particles, if they are stable to some extent. Since the electron mass is relatively small, one needs an initial radius of about  $4 \times 10^{-13}$  m in order to be able to neglect the influence of spin, charge, magnetic moment to some extent, see Fig. 3 [7]. One step count maximum (piled) appears fairly correctly at the experimental value, flanked by adjoining maxima, possibly caused by the neglected parameters.

The success in detecting known masses gives us confidence for trying a prediction of neutrino masses. That implies that neutrinos are stationary particles, i.e. have rest mass at all. Then they can never reach light speed.

The Particle Data Group [12] commented in the year 2002:

*There is now compelling evidence that neutrinos have nonzero mass from the observation of neutrino flavor change, both from the study of atmospheric neutrino fluxes by SuperKamiokande, and from the combined study of solar neutrino cross sections by SNO (charged and neutral currents) and SuperKamiokande (elastic scattering).*

The neutrino has the advantage of being electromagnetically neutral. As well, the spin does not perceptibly influence other components of metrics than those for the spin itself. So we can unscrupulously neglect the spin, and

search for quite tiny masses.

Quoting the Particle Data Group (in 2002) again [12]:

*Mass*<sup>5</sup>  $m < 3 \text{ eV}$ .

*Interpretation of tritium beta decay experiments is complicated by anomalies near the endpoint, and the limits are not without ambiguity.*

Newer experiments re-verify this ambiguity, just providing multiple mass bounds.

Ten plausible maxima have been found in our calculations for the electron neutrino, see Figs. 4, 5, 6, 7, 8, (quoted from [7]) and the supplementary data. Obtained values are 0.068 eV, 0.095 eV, 0.155 eV, 0.25 eV, 0.31 eV, 0.39 eV, 0.56 eV, 1.63 eV, 2.88 eV, 5.7 eV. Smaller values are less convincing.

The mentioned ambiguity gets along with the fact that multiple mass values have been detected. It could be possible that the set of values is reduced by computation with spin. The precision with 80 bit registers is not sufficient for such calculations. However, it could well be possible interpreting some values as composites from smaller values. Here we could have comparable circumstances like in nuclei so that there is no reason for the assumption that only one value can exist. This conclusion is supported by multiple experimental mass bound values.

Many mass values are integer multiples of  $\sim 0.08 \text{ eV}$ , within the tolerances of the method. At the place of this value there is a hole in the figure, flanked by maxima at 0.068 eV and 0.095 eV. This could be:

- 1) a methodical error, or an effect of overdriving, known from electrical engineering,
- 2) both values are a kind of basic values, where the other values are composites from.

Other interpretations cannot be precluded.

## 8 Conclusion

It has been shown in this paper that the singularity problem is irrelevant for geometric equations, just for those of the RAINICH space, the known EINSTEIN-MAXWELL equations. So these equations can be numerically solved. Even more, the discrete values of particle quantities, for example neutrino masses, can be predicted by numerical calculations based on EINSTEIN-MAXWELL theory. Starting from a finite difference scheme for

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<sup>5</sup>of electron neutrino

differential equations, chaos properties of these equations were investigated in dependence of parameters being integration constants of the theory.

The resulting masses for supposed electron neutrinos come out to lie in the range being known by experiments. This is probably the first time that neutrino masses are predicted by a theory based on first principles.

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We express our thank to Bernhard FOLTZ who suggested searching for neutrino masses according to the described numerical method. Also, he reported the state of experimental neutrino research.

**Appendix: Basic formulae of general relativity**

The tensor calculus is a lot more clear than conventional vector analysis so that the formalism of the general theory of relativity [5] is reduced to few formulae:

The BIANCHI identities [6]

$$(R_i^k - \frac{1}{2}R\delta_i^k)_{;k} = 0$$

are always fulfilled by

$$R_{ik} = 0 \quad .$$

Therefore, only 6 independent equations exist for 10 components  $g_{ik}$ . If we set (EINSTEIN and GROSSMANN [5])

$$R_{ik} - \frac{1}{2}Rg_{ik} = -\kappa T_{ik} \quad ,$$

the divergences of the energy tensor must vanish

$$T_i^k{}_{;k} = 0 \quad ,$$

as dictated by nature. For the variables in the energy tensor, separate conditions follow, which do not take the place of the lacking conditions in metrics.

The divergences of the energy tensor of distributed mass

$$T^{ik} = \sigma \frac{dx^i}{ds} \frac{dx^k}{ds}$$

with the mass density  $\sigma$  are

$$T_{;k}^{ik} = \sigma k^i$$

with the (space-like) curvature vector  $\mathbf{k}$ . One can see the equivalence principle [5] in the curvature vector, because the curvature vector consists of accelerated motion and the gravitational field. - Since the curvature vector of any time-like curve in space-time is different from zero in general,  $\sigma$  must be zero everywhere. Distributed mass does not exist.

There is an exception when we start from discrete masses (which can only be integration constants). The force onto a body with the mass  $m$  then were

$$K^i = m k^i \quad .$$

For force equilibrium it must be  $k^i = 0$  . That results in four equations of motion. The curve described by the body in space-time is a geodesic.

The electromagnetic energy tensor (LORENTZ, see EINSTEIN [5])

$$T_{ik} = F_{ia} F_k^a - \frac{1}{4} g_{ik} F_{ab} F^{ab}$$

would result in a force density (LORENTZ force)

$$T_{;k}^{ik} = F^i{}_a S^a \quad ,$$

i. e.  $\mathbf{S}$  must be zero. That means, there are no distributed charges and currents. Discrete charges are analogous to discrete masses. Equations of motions result together with the mass (the curves are no geodesics then).

From this we see:

- 1) Complete determinacy is not given.
- 2) There are no distributed charges and masses (sources).
- 3) Only the electromagnetic energy tensor is applicable in EINSTEIN's gravitational equation.
- 4) In order to calculate fields (gravitational and electromagnetic), we have to deal with integration constants instead of sources.

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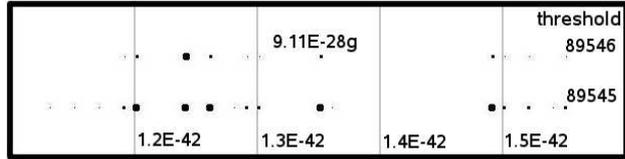


Figure 3: Tests for the free electron. Initial radius 400, 51 values, 9 times piled (459 tests)

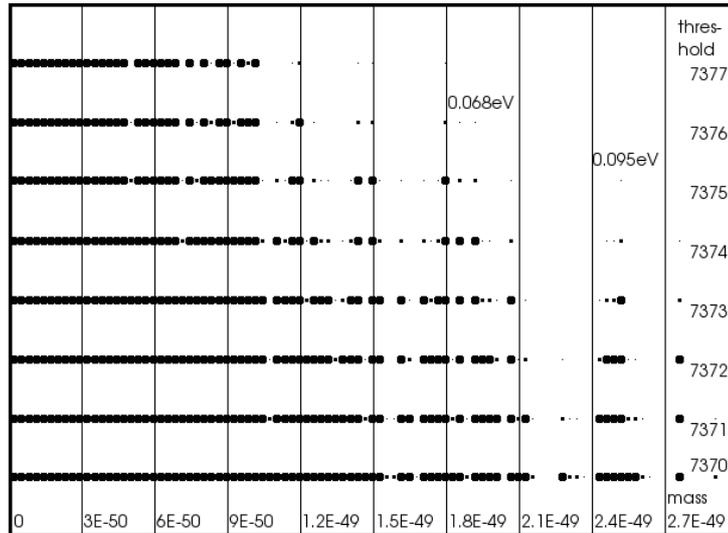


Figure 4: Tests for the electron neutrino, masses  $< 0.11$  eV. Initial radius 5, 100 values, 9 times piled (900 tests)

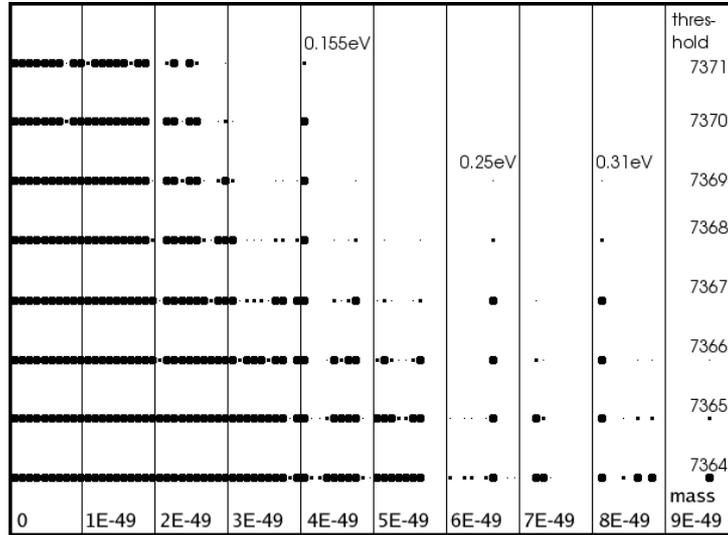


Figure 5: Tests for the electron neutrino, masses  $< 0.4 \text{ eV}$ . Initial radius 5, 100 values, 9 times piled (900 tests)

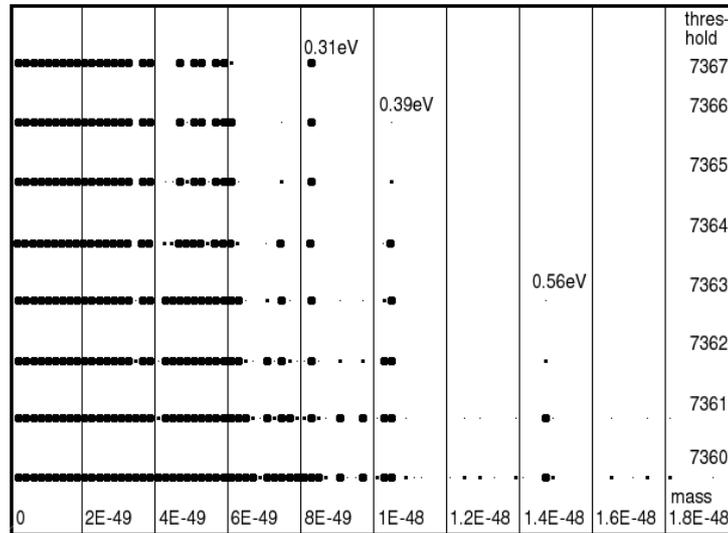


Figure 6: Tests for the electron neutrino, masses  $< 1 \text{ eV}$ . Initial radius 5, 99 values, 9 times piled (891 tests)

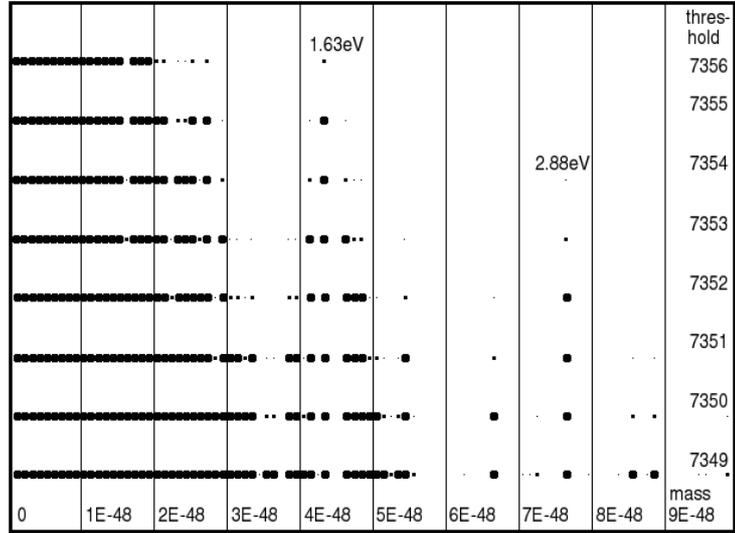


Figure 7: Tests for the electron neutrino, masses  $< 4\text{ eV}$ . Initial radius 5, 99 values, 9 times piled (891 tests)

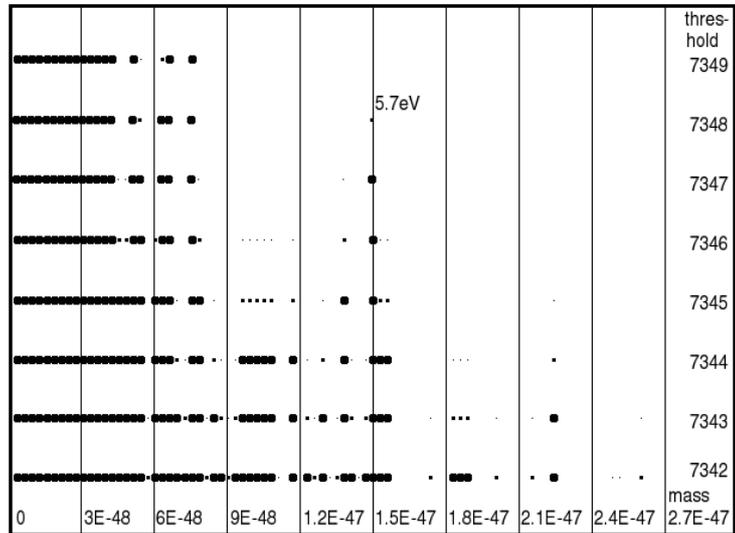


Figure 8: Tests for the electron neutrino, masses  $< 11\text{ eV}$ . Initial radius 5, 100 values, 9 times piled (900 tests)