

Refutation of surveillance objectives

© Copyright 2018 by Colin James III All rights reserved.

Abstract: We evaluate an equivalence and theorem. Neither are tautologous. Hence the reduction of the multi-agent surveillance synthesis problem to solving single-sensor surveillance subgames is refuted. What follows is that surveillance objectives are *non* tautologous fragments of the universal logic $\forall\exists\forall$.

We assume the method and apparatus of Meth8/ $\forall\exists\forall$ with Tautology as the designated proof value, **F** as contradiction, **N** as truthity (non-contingency), and **C** as falsity (contingency). The 16-valued truth table is row-major and horizontal, or repeating fragments of 128-tables, sometimes with table counts, for more variables. (See ersatz-systems.com.)

LET \sim Not, \neg ; + Or, \vee , \cup ; - Not Or; & And, \wedge , \cap , \cdot ; \ Not And;
 $>$ Imply, greater than, \rightarrow , \mapsto , \succ , \supset , \vdash , \models , \Rightarrow ; $<$ Not Imply, less than, \in , $<$, \subset , \neq , \neq , \leftarrow ;
 $=$ Equivalent, \equiv , $:=$, \iff , \leftrightarrow , \triangleq , \approx ; @ Not Equivalent, \neq ;
 $\%$ possibility, for one or some, \exists , \diamond , **M**; # necessity, for every or all, \forall , \square , **L**;
 $(z=z)$ **T** as tautology, \top , ordinal 3; $(z@z)$ **F** as contradiction, \emptyset , Null, \perp , zero;
 $(\%z<\#z)$ **C** as contingency, Δ , ordinal 1; $(\%z>\#z)$ **N** as non-contingency, ∇ , ordinal 2;
 $\sim(y < x)$ ($x \leq y$), ($x \subseteq y$); $(A=B)$ ($A\sim B$).
 Note: For clarity we usually distribute quantifiers on each variable as designated.

From: Bharadwa, S.; Dimitrova, R.; Topcu, U. (2019).
 Distributed synthesis of surveillance strategies for mobile sensors.
arxiv.org/pdf/1902.02393.pdf suda.b@utexas.edu

D. Temporal surveillance objectives

In this paper we consider safety and liveness surveillance objectives, as well as conjunctions of such objectives. We remark the following equivalences of surveillance objectives: ...

$$\text{if } a \leq b, \text{ then } \square p_a \wedge \square \diamond p_b \equiv \square p_a \quad (\text{D.1.1})$$

LET p, q, r, s : p, q, a, b

$$\sim(s < r) > (((\#p \& q) \& (\#\%p \& s)) = (\#p \& r)) ; \quad \text{TTTT TCTC TTTT TCTC} \quad (\text{D.1.2})$$

Using these equivalences, we can restrict our attention to surveillance objectives of one the following forms:

$$\square p_b, [\text{or}] \square \diamond p_b[,], \text{ or } \square p_a \wedge \square \diamond p_b, \text{ where } a > b \quad (\text{D.2.1})$$

$$(r > s) > (((\#p \& s) + (\#\%p \& s)) + ((\#p \& r) \& (\#p \& s))) ; \quad \text{FFFF TTTT CTCT CTCT} \quad (\text{D.2.2})$$

Eqs. D.1.2 and D2.2 are *not* tautologous. This means the equivalences of the surveillance objective forms are *not* tautologous. Hence the reduction of the multi-agent surveillance synthesis problem to solving single-sensor surveillance subgames is refuted.