

The sixth Dimension

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ABSTRACT

Assume mass and electric current are Fifth and sixth dimensions in Special Relativity and Redefinition of the point as a circle. According to Einstein's first hypothesis only it can be reached to transfer formats between reference frames in the special theory of relativity

Keywords

The fifth dimension, the sixth dimension,

Introduction

Redefinition of the point

Redefinition of the point as a circle the length of it the radius Equal the length of the Planck cT_{pl}

SO
$$dX_1 = vdT_1 \sqrt{1 - \frac{v^2}{c^2} \left(1 - \left(\frac{dX_{pl}^2}{dX_1^2}\right)\right)}$$

$$dX_1 = v \sqrt{dT_1^2 - \frac{c^2}{v^2} (dT_{pl}^2)}$$

$$dX_1 = vdT_1 \sqrt{1 - \frac{c^2}{v^2} \left(\frac{dT_{pl}^2}{dT_1^2}\right)}$$

$$dX_1 = vdT_1 \sqrt{1 - \frac{v^2}{c^2} \left(1 - \left(\frac{dX_{pl}^2}{dX_1^2}\right)\right)}$$

contribution

Consider two observers A , B in both frames S_1 , S_2

At first $dT_1 = dT_2 = 0$

T_1 The time at frame S_1 and T_2 the time at frame S_2

Let A and B in the same place and at the same time, they each send a light signal

Let S_2 and (observer B) moving respect to S_1 and (observer A) with uniform Velocity \vec{V}

At the direction of the axis \vec{ox}

In this case the signal is spread as a spherical wave

Measurements A:

At moment dT_1 of his watch, the wave equation appears in the Formula:

$$dX_1^2 + dY_1^2 + dZ_1^2 - C_1^2 dT_1^2 - \frac{G_1^2}{C_{M1}^4} dM_1^2 - \frac{K_{e1} \hbar_1 G_1^2}{C_{I1}^9} dI_1^2 = 0 \quad \text{----- (1)}$$

C_1 Speed of light, C_{M1} Speed of light at mass dimension at frame S_1

And C_{I1} Speed of light at church dimension at frame S_1

Measurements B:

At moment T_2 of his watch, the wave equation appears in the Formula:

$$dX_2^2 + dY_2^2 + dZ_2^2 - C_2^2 dT_2^2 - \frac{G_2^2}{C_{M2}^4} dM_2^2 - \frac{K_{e2} \hbar_2 G_2^2}{C_{I2}^9} dI_2^2 = 0 \quad \text{----- (2)}$$

C_2 Speed of light and C_{M2} Speed of light at mass dimension at frame S_2

And C_{I2} Speed of light at church dimension at frame S_2

Notice $C_1 \neq C_2$

Then

$$dX_1^2 + dY_1^2 + dZ_1^2 - C_1^2 dT_1^2 - \frac{G_1^2}{C_{M1}^4} dM_1^2 - \frac{K_{e1} \hbar_1 G_1^2}{C_{I1}^9} dI_1^2 =$$

$$dX_2^2 + dY_2^2 + dZ_2^2 - C_2^2 dT_2^2 - \frac{G_2^2}{C_{M2}^4} dM_2^2 - \frac{K_{e2} \hbar_2 G_2^2}{C_{I2}^9} dI_2^2 \quad \text{----- (3)}$$

Let $dY_1 = dY_2$ and $dZ_1 = dZ_2$

So

$$dX_1^2 - C_1^2 dT_1^2 - \frac{G_1^2}{C_{M1}^4} dM_1^2 - \frac{K_{e1} \hbar_1 G_1^2}{C_{I1}^9} dI_1^2 =$$

$$dX_2^2 - C_2^2 dT_2^2 - \frac{G_2^2}{C_{M2}^4} dM_2^2 - \frac{K_{e2} \hbar_2 G_2^2}{C_{I2}^9} dI_2^2 \text{ ----- (4)}$$

Let

$$dX_2 = G_{11} dX_1 + G_{14} dT_1 + G_{15} dM_1 + G_{16} dI_1 \text{ ----- (5)}$$

$$dT_2 = G_{41} dX_1 + G_{44} dT_1 + G_{45} dM_1 + G_{46} dI_1 \text{ ----- (6)}$$

$$dM_2 = G_{51} dX_1 + G_{54} dT_1 + G_{55} dM_1 + G_{56} dI_1 \text{ ----- (7)}$$

$$dI_2 = G_{61} dX_1 + G_{64} dT_1 + G_{65} dM_1 + G_{66} dI_1 \text{ ----- (8)}$$

Where $G_{11}, G_{14}, G_{15}, G_{16}, G_{41}, G_{44}, G_{45}, G_{46}, G_{51}, G_{54}, G_{55}, G_{56}, G_{61}, G_{64}, G_{65}, G_{66}$. are constants

Consider the moving of origin point O_2 respect to S_1

(Ordinates O_2) is $dX_2=0$

So from equation (5)

$$dX_2 = G_{11} dX_1 + G_{14} dT_1 + G_{15} dM_1 + G_{16} dI_1 \text{ ----- (5)}$$

$$0 = G_{11} dX_1 + G_{14} dT_1 + G_{15} dM_1 + G_{16} dI_1$$

$$G_{14} dT_1 = -G_{11} dX_1 - G_{15} dM_1 - G_{16} dI_1$$

$$G_{14} = -G_{11} \frac{dX_1}{dT_1} - G_{15} \frac{dM_1}{dT_1} - G_{16} \frac{dI_1}{dT_1} \quad \text{And} \quad \frac{dX_1}{dT_1} = v \sqrt{1 - \frac{c_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2} \right)}$$

$$\text{So} \quad G_{14} = -G_{11} v \sqrt{1 - \frac{c_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2} \right)} - G_{15} \frac{dM_1}{dT_1} - G_{16} \frac{dI_1}{dT_1} \text{ ----- (9)}$$

Consider the moving of origin point O_1 respect to S_2

(Ordinates O_1) is $dX_1=0$

So from equation (5)

$$dX_2 = G_{11} dX_1 + G_{14} dT_1 + G_{15} dM_1 + G_{16} dI_1 \text{ ----- (5)}$$

$$dX_2 = 0 + G_{14} dT_1 + G_{15} dM_1 + G_{16} dI_1$$

$$dX_2 = G_{14} dT_1 + G_{15} dM_1 + G_{16} dI_1 \text{ ----- (10)}$$

From equation (6)

$$dT_2 = G_{41} dX_1 + G_{44} dT_1 + G_{45} dM_1 + G_{46} dI_1 \text{ ----- (6)}$$

$$dT_2 = 0 + G_{44} dT_1 + G_{45} dM_1 + G_{46} dI_1$$

$$dT_2 = G_{44} dT_1 + G_{45} dM_1 + G_{46} dI_1 \quad \text{-----} \quad (11)$$

From equation (8) and (9)

$$\frac{dX_2}{dT_2} = \frac{G_{14} dT_1 + G_{15} dM_1 + G_{16} dI_1}{G_{44} dT_1 + G_{45} dM_1 + G_{46} dI_1} \quad \text{And} \quad \frac{dX_2}{dT_2} = -v \sqrt{1 - \frac{c_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2} \right)}$$

$$\text{So} \quad \frac{G_{14} dT_1 + G_{15} dM_1 + G_{16} dI_1}{G_{44} dT_1 + G_{45} dM_1 + G_{46} dI_1} = -v \sqrt{1 - \frac{c_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2} \right)}$$

From equation (7)

$$G_{14} = -G_{11} v \sqrt{1 - \frac{c_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2} \right)} - G_{15} \frac{dM_1}{dT_1} - G_{16} \frac{dI_1}{dT_1} \quad \text{-----} \quad (9)$$

So

$$\frac{G_{14} dT_1 + G_{15} dM_1 + G_{16} dI_1}{G_{44} dT_1 + G_{45} dM_1 + G_{46} dI_1} = -v \sqrt{1 - \frac{c_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2} \right)}$$

$$\frac{-G_{11} v dT_1 \sqrt{1 - \frac{c_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2} \right)} - G_{15} dM_1 - G_{16} dI_1 + G_{15} M_1 + G_{16} dI_1}{G_{44} dT_1 + G_{45} dM_1 + G_{46} dI_1} = -v \sqrt{1 - \frac{c_1^2}{v^2} \left(\frac{T_{PL}^2}{T_1^2} \right)}$$

$$\frac{-G_{11} v dT_1 \sqrt{1 - \frac{c_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2} \right)}}{G_{44} dT_1 + G_{45} dM_1 + G_{46} dI_1} = -v \sqrt{1 - \frac{c_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2} \right)}$$

$$\frac{G_{11} dT_1}{G_{44} dT_1 + G_{45} dM_1 + G_{46} dI_1} = 1$$

$$G_{44} dT_1 + G_{45} dM_1 + G_{46} dI_1 = G_{11} dT_1$$

$$G_{44} = G_{11} - G_{45} \frac{dM_1}{dT_1} - G_{46} \frac{dI_1}{dT_1} \quad \text{-----} \quad (12)$$

From equations (6), (7)

$$dT_2 = G_{41} dX_1 + G_{44} dT_1 + G_{45} dM_1 + G_{46} dI_1 \quad \text{-----} \quad (6)$$

$$dM_2 = G_{51} dX_1 + G_{54} dT_1 + G_{55} dM_1 + G_{56} dI_1 \quad \text{-----} \quad (7)$$

$$dX_1 = 0$$

$$dT_2 = G_{44} dT_1 + G_{45} dM_1 + G_{46} dI_1$$

$$dM_2 = G_{54} dT_1 + G_{55} dM_1 + G_{56} dI_1$$

So

$$\frac{dM_2}{dT_2} = \frac{G_{54} dT_1 + G_{55} dM_1 + G_{56} dI_1}{G_{44} dT_1 + G_{45} dM_1 + G_{46} dI_1} \quad \text{And} \quad \frac{dM_2}{dT_2} = \frac{dM_1}{dT_1}$$

$$\frac{dM_2}{dT_2} = \frac{G_{54} dT_1 + G_{55} dM_1 + G_{56} dI_1}{G_{44} dT_1 + G_{45} dM_1 + G_{46} dI_1}$$

$$\frac{dM_2}{dT_2} = \frac{G_{54} + G_{55} \frac{dM_1}{dT_1} + G_{56} \frac{dI_1}{dT_1}}{G_{44} + G_{45} \frac{M_1}{T_1} + G_{46} \frac{dI_1}{dT_1}}$$

From

$$G_{44} = G_{11} - G_{45} \frac{dM_1}{dT_1} - G_{46} \frac{dI_1}{dT_1} \quad \text{-----} \quad (12)$$

$$\frac{dM_2}{dT_2} = \frac{G_{54} + G_{55} \frac{dM_1}{dT_1} + G_{56} \frac{dI_1}{dT_1}}{G_{11} - G_{45} \frac{dM_1}{dT_1} - G_{46} \frac{dI_1}{dT_1} + G_{45} \frac{M_1}{T_1} + G_{46} \frac{dI_1}{dT_1}}$$

$$\frac{dM_2}{dT_2} = \frac{G_{54} + G_{55} \frac{dM_1}{dT_1} + G_{56} \frac{dI_1}{dT_1}}{G_{11}}$$

$$G_{54} + G_{55} \frac{dM_1}{dT_1} + G_{56} \frac{dI_1}{dT_1} = G_{11} \frac{dM_2}{dT_2}$$

$$G_{54} = G_{11} \frac{dM_2}{dT_2} - G_{55} \frac{dM_1}{dT_1} - G_{56} \frac{dI_1}{dT_1} \quad \text{-----} \quad (13)$$

From (5), (9)

$$dX_2 = G_{11} dX_1 + G_{14} dT_1 + G_{15} dM_1 + G_{16} dI_1 \quad \text{-----} \quad (5)$$

$$G_{14} = -G_{11} v \sqrt{1 - \frac{c_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2} \right)} - G_{15} \frac{dM_1}{dT_1} - G_{16} \frac{dI_1}{dT_1} \quad \text{-----} \quad (9)$$

$$dX_2 = G_{11} dX_1 - G_{11} v dT_1 \sqrt{1 - \frac{c_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2} \right)} - G_{15} dM_1 - G_{16} dI_1 + G_{15} dM_1 + G_{16} dI_1 \quad \text{-----} \quad (14)$$

$$dX_2 = G_{11} dX_1 - G_{11} v dT_1 \sqrt{1 - \frac{c_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2} \right)}$$

$$dX_2 = G_{11} [dX_1 - v dT_1 \sqrt{1 - \frac{c_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2} \right)}] \quad \text{-----} \quad (15)$$

From (6), (12)

$$dT_2 = G_{41} dX_1 + G_{44} dT_1 + G_{45} dM_1 + G_{46} dI_1 \text{ ----- (6)}$$

$$G_{44} = G_{11} - G_{45} \frac{dM_1}{dT_1} - G_{46} \frac{dI_1}{dT_1} \text{ ----- (12)}$$

$$dT_2 = G_{41} dX_1 + G_{11} dT_1 - G_{45} dM_1 - G_{46} dI_1 + G_{45} dM_1 + G_{46} dI_1$$

$$dT_2 = G_{41} dX_1 + G_{11} dT_1 \text{ ----- (16)}$$

From (7), (13)

$$dM_2 = G_{51} dX_1 + G_{54} dT_1 + G_{55} dM_1 + G_{56} dI_1 \text{ ----- (7)}$$

$$G_{54} = G_{11} \frac{dM_2}{dT_2} - G_{55} \frac{dM_1}{dT_1} - G_{56} \frac{dI_1}{dT_1} \text{ ----- (13)}$$

$$dM_2 = G_{51} dX_1 + G_{54} dT_1 + G_{55} dM_1 + G_{56} dI_1$$

$$dM_2 = G_{51} dX_1 + G_{11} dM_1 - G_{55} dM_1 - G_{56} dI_1 + G_{55} dM_1 + G_{56} dI_1$$

$$dM_2 = G_{51} dX_1 + G_{11} dM_1 \text{ ----- (17)}$$

From (6), (8)

$$dT_2 = G_{41} dX_1 + G_{44} dT_1 + G_{45} dM_1 + G_{46} dI_1 \text{ ----- (6)}$$

$$dI_2 = G_{61} dX_1 + G_{64} dT_1 + G_{65} dM_1 + G_{66} dI_1 \text{ ----- (8)}$$

$$dX_1 = 0$$

$$dT_2 = G_{44} dT_1 + G_{45} dM_1 + G_{46} dI_1$$

$$dI_2 = G_{64} dT_1 + G_{65} dM_1 + G_{66} dI_1$$

$$\frac{dI_2}{dT_2} = \frac{G_{64} dT_1 + G_{65} dM_1 + G_{66} dI_1}{G_{44} dT_1 + G_{45} dM_1 + G_{46} dI_1} \text{ and } \frac{dI_2}{dT_2} = \frac{dI_1}{dT_1}$$

$$\frac{dI_1}{dT_1} = \frac{G_{64} + G_{65} \frac{dM_1}{dT_1} + G_{66} \frac{dI_1}{dT_1}}{G_{44} + G_{45} \frac{dM_1}{dT_1} + G_{46} \frac{dI_1}{dT_1}}$$

From

$$G_{44} = G_{11} - G_{45} \frac{dM_1}{dT_1} - G_{46} \frac{dI_1}{dT_1} \text{ ----- (12)}$$

$$\frac{dl_1}{dT_1} = \frac{G_{64} + G_{65} \frac{dM_1}{dT_1} + G_{66} \frac{dl_1}{dT_1}}{G_{11} - G_{45} \frac{dM_1}{dT_1} - G_{46} \frac{dl_1}{dT_1} + G_{45} \frac{dM_1}{dT_1} + G_{46} \frac{dl_1}{dT_1}}$$

$$\frac{dl_1}{dT_1} = \frac{G_{64} + G_{65} \frac{dM_1}{dT_1} + G_{66} \frac{dl_1}{dT_1}}{G_{11}}$$

$$G_{64} + G_{65} \frac{dM_1}{dT_1} + G_{66} \frac{dl_1}{dT_1} = G_{11} \frac{dl_1}{dT_1}$$

$$G_{64} = G_{11} \frac{dl_1}{dT_1} - G_{65} \frac{dM_1}{dT_1} - G_{66} \frac{dl_1}{dT_1} \dots \dots \dots (18)$$

From (8), (18)

$$dl_2 = G_{61} dX_1 + G_{64} dT_1 + G_{65} dM_1 + G_{66} dl_1 \dots \dots \dots (8)$$

$$G_{64} = G_{11} \frac{dl_1}{dT_1} - G_{65} \frac{dM_1}{dT_1} - G_{66} \frac{dl_1}{dT_1} \dots \dots \dots (18)$$

$$dl_2 = G_{61} dX_1 + G_{11} dq_1 - G_{65} dM_1 - G_{66} dl_1 + G_{65} dM_1 + G_{66} dl_1$$

$$dl_2 = G_{61} dX_1 + G_{11} dl_1 \dots \dots \dots (19)$$

$$dX_1^2 - C_1^2 dT_1^2 - \frac{G_1^2}{C_{M1}^4} dM_1^2 - \frac{K_{e1} \hbar_1 G_1^2}{C_{I1}^9} dl_1^2 =$$

$$dX_2^2 - C_2^2 dT_2^2 - \frac{G_2^2}{C_{M2}^4} dM_2^2 - \frac{K_{e2} \hbar_2 G_2^2}{C_{I2}^9} dl_2^2 \dots \dots \dots (4)$$

From (15), (16), (17), (19)

$$dX_2 = G_{11} [dX_1 - vdT_1 \sqrt{1 - \frac{C_1^2}{v^2} (\frac{dT_{PL}^2}{dT_1^2})}] \dots \dots \dots (15)$$

$$dT_2 = G_{41} dX_1 + G_{11} dT_1 \dots \dots \dots (16)$$

$$dM_2 = G_{51} dX_1 + G_{11} dM_1 \dots \dots \dots (17)$$

$$dl_2 = G_{61} dX_1 + G_{11} dl_1 \dots \dots \dots (19)$$

$$\begin{aligned}
dX_1^2 - C_1^2 dT_1^2 - \frac{G_1^2}{C_{M1}^4} dM_1^2 - \frac{K_{e1} \hbar_1 G_1^2}{C_{I1}^9} dI_1^2 \\
= (G_{11} [X_1 - v T_1 \sqrt{1 - \frac{C_1^2}{v^2} \left(\frac{T_{PL}^2}{T_1^2} \right)}])^2 - C_2^2 (G_{41} X_1 + G_{11} T_1)^2 - \frac{G_2^2}{C_{M2}^4} (G_{51} X_1 + G_{11} M_1)^2 \\
- \frac{K_{e2} \hbar_2 G_2^2}{C_{I2}^9} dI_2^2 (G_{61} dX_1 + G_{11} dI_1)^2
\end{aligned}$$

----- (20)

Compare the coefficient of dX_1^2

$$1 = G_{11}^2 - C_2^2 (G_{41})^2 - \frac{G_2^2}{C_{M2}^4} (G_{51})^2$$

$$G_{11}^2 = 1 + C_2^2 (G_{41})^2 + \frac{G_2^2}{C_{M2}^4} (G_{51})^2$$

----- (21)

Compare the coefficient of $dX_1 dT_1$

$$0 = -2v \sqrt{1 - \frac{C_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2} \right)} G_{11}^2 - 2C_2^2 (G_{41} G_{11})$$

$$0 = v \sqrt{1 - \frac{C_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2} \right)} G_{11}^2 + C_2^2 (G_{41} G_{11})$$

$$v \sqrt{1 - \frac{C_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2} \right)} G_{11}^2 = -C_2^2 (G_{41} G_{11})$$

$$v \sqrt{1 - \frac{C_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2} \right)} G_{11} = -C_2^2 (G_{41})$$

$$G_{11} = \frac{-C_2^2}{v \sqrt{1 - \frac{C_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2} \right)}} (G_{41})$$

$$G_{41} = \frac{-v \sqrt{1 - \frac{C_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2} \right)}}{C_2^2} (G_{11}) \text{ ----- (22)}$$

$$dT_2 = G_{41} dX_1 + G_{11} dT_1 \text{----- (16)}$$

$$dT_2 = \frac{-v \sqrt{1 - \frac{c_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2} \right)}}{c_2^2} (G_{11}) dX_1 + G_{11} dT_1$$

$$dT_2 = G_{11} \left(dT_1 - \frac{v \sqrt{1 - \frac{c_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2} \right)}}{c_2^2} dX_1 \right) \dots\dots\dots (23)$$

Compare the coefficient of dT_1^2

$$-C_1^2 = G_{11}^2 \left(-v \sqrt{1 - \frac{c_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2} \right)} \right)^2 - C_2^2 (G_{11})^2$$

$$-C_1^2 = G_{11}^2 \left[v^2 \left(1 - \frac{c_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2} \right) - C_2^2 \right) \right]$$

$$1 = G_{11}^2 \left[\frac{-v^2}{C_1^2} \left(1 - \frac{c_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2} \right) + \frac{C_2^2}{C_1^2} \right) \right]$$

$$G_{11} = \frac{1}{\sqrt{\frac{C_2^2}{C_1^2} - \frac{v^2}{C_1^2} \left(1 - \frac{c_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2} \right) \right)}} \dots\dots\dots (24)$$

Compare the coefficient of dM_1^2

$$-\frac{G_1^2}{C_{M1}^4} = -\frac{G_2^2}{C_{M2}^4} G_{11}^2$$

Compare the coefficient of $dM_1 dX_1$

$$0 = -2 \frac{G_2^2}{C_{M2}^4} G_{51} G_{11}$$

$$C_{M2} \neq 0, G_2 \neq 0, G_{11} \neq 0$$

$$SO \quad G_{51} = 0$$

$$dM_2 = G_{51} dX_1 + G_{11} dM_1 \dots\dots\dots (25)$$

$$dM_2 = G_{11} dM_1 \dots\dots\dots (20)$$

From Equation (16)

$$G_{11}^2 = 1 + C_2^2 (G_{41})^2 + \frac{G_2^2}{C_{M2}^4} (G_{51})^2 \dots\dots\dots (16)$$

$$G_{51} = 0 \dots\dots\dots (16)$$

So $G_{11}^2 = 1 + C_2^2(G_{41})^2$

$$G_{41} = \frac{-v \sqrt{1 - \frac{C_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2}\right)}}{C_2^2} (G_{11}) \dots\dots\dots (17)$$

$$G_{11}^2 = 1 + C_2^2 \left(\frac{-v \sqrt{1 - \frac{C_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2}\right)}}{C_2^2} (G_{11}) \right)^2$$

$$G_{11}^2 = 1 + G_{11}^2 \frac{v^2}{C_2^2} \left(1 - \frac{C_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2}\right)\right)$$

$$G_{11}^2 \left(1 - \frac{v^2}{C_2^2} \left(1 - \frac{C_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2}\right)\right)\right) = 1$$

$$G_{11} = \frac{1}{\sqrt{1 - \frac{v^2}{C_2^2} \left(1 - \frac{C_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2}\right)\right)}} \dots\dots\dots (21)$$

From (18), (20)

$$G_{11} = \frac{1}{\sqrt{\frac{C_2^2}{C_1^2} - \frac{v^2}{C_1^2} \left(1 - \frac{C_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2}\right)\right)}} \dots\dots\dots (19)$$

$$G_{11} = \frac{1}{1 - \sqrt{1 - \frac{v^2}{C_2^2} \left(1 - \frac{C_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2}\right)\right)}} \dots\dots\dots (21)$$

$$\frac{1}{\sqrt{\frac{C_2^2}{C_1^2} - \frac{v^2}{C_1^2} \left(1 - \frac{C_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2}\right)\right)}} = \frac{1}{1 - \sqrt{1 - \frac{v^2}{C_2^2} \left(1 - \frac{C_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2}\right)\right)}}$$

$$\frac{C_2^2}{C_1^2} - \frac{v^2}{C_1^2} \left(1 - \frac{C_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2}\right)\right) = 1 - \frac{v^2}{C_2^2} \left(1 - \frac{C_1^2}{v^2} \left(\frac{dT_{PL}^2}{dT_1^2}\right)\right)$$

$$\frac{C_2^2}{C_1^2} - \frac{v^2}{C_1^2} - \left(\frac{dT_{PL}^2}{dT_1^2}\right) = 1 - \frac{v^2}{C_2^2} - \frac{C_1^2}{C_2^2} \left(\frac{dT_{PL}^2}{dT_1^2}\right)$$

Compare the coefficient of $\left(\frac{dT_{PL}^2}{dT_1^2}\right)$

$$\frac{C_1^2}{C_2^2} = 1$$

Then $C_1^2 = C_2^2$

So $C_1 = \pm C_2$

Let $C_1^2 = C_2^2 = C^2$ ----- (22)

And $G_{11} = \gamma$

$$G_{11} = \frac{1}{\sqrt{\frac{C_2^2}{C_1^2} - \frac{v^2}{C_1^2} (1 - \frac{C_1^2}{v^2} (\frac{dT_{PL}^2}{dT_1^2}))}} \text{----- (19)}$$

$$\gamma = \frac{1}{\sqrt{1 - \frac{v^2}{C^2} (1 - \frac{C^2}{v^2} (\frac{dT_{PL}^2}{dT_1^2}))}}$$

$$\gamma = \frac{1}{\sqrt{1 - \frac{v^2}{C^2} (1 - (\frac{dX_{PL}^2}{dX_1^2}))}} \text{----- (23)}$$

$$dX_2 = G_{11} [dX_1 - v dT_1 \sqrt{1 - \frac{C_1^2}{v^2} (\frac{dT_{PL}^2}{dT_1^2})}] \text{----- (12)}$$

$$dT_2 = G_{11} (dT_1 - \frac{v \sqrt{1 - \frac{C_1^2}{v^2} (\frac{dT_{PL}^2}{dT_1^2})}}{C_2^2} dX_1) \text{----- (18)}$$

$$dM_2 = G_{11} dM_1 \text{----- (20)}$$

$$C_1^2 = C_2^2 = C^2 \text{----- (22)}$$

$$\gamma = \frac{1}{\sqrt{1 - \frac{v^2}{C^2} (1 - (\frac{dX_{PL}^2}{dX_1^2}))}} \text{----- (23)}$$

$$dX_2 = \gamma [dX_1 - v dT_1 \sqrt{1 - \frac{dX_{PL}^2}{dX_1^2}}] \text{----- (24)}$$

$$dT_2 = \gamma (dT_1 - \frac{v \sqrt{1 - \frac{dX_{PL}^2}{dX_1^2}}}{C_2^2} X_1) \text{----- (25)}$$

$$dM_2 = \gamma dM_1 \text{----- (26)}$$

Compare the coefficient of $dI_1 dX_1$

$$0 = -2 \frac{K_{e2} \hbar_2 G_2^2}{C_{I2}^9} dI_2^2 G_{61} G_{11}$$

$$C_{q2} \neq 0, G_2 \neq 0, K_{e2} \neq 0, G_{11} \neq 0, \hbar_2 \neq 0$$

SO $G_{61} = 0$

From Equation (19)

$$dl_2 = G_{61} dX_1 + G_{11} dl_1 \text{-----} (19)$$

$$dl_2 = 0 + G_{11} dl_1$$

$$dl_2 = G_{11} dl_1 \text{-----} (27)$$

Conclusion

Lorentz Transformations

$$dX_2 = \gamma [dX_1 - v dT_1 \sqrt{1 - \frac{dX_{PL}^2}{dX_1^2}}] \text{-----} (24)$$

$$dT_2 = \gamma (dT_1 - \frac{v \sqrt{1 - \frac{dX_{PL}^2}{dX_1^2}}}{c^2} dX_1) \text{-----} (25)$$

$$dM_2 = \gamma dM_1 \text{-----} (26)$$

$$dl_2 = \gamma dl_1 \text{-----} (30)$$

$$\gamma = \frac{1}{\sqrt{1 - \frac{v^2}{c^2} (1 - \frac{dX_{PL}^2}{dX_1^2})}} \text{-----} (23)$$

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