## No blowup for the Navier-Stokes equations

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A proposed solution to the millennium problem on the existence and smoothness of the Navier–Stokes equations.

## 1. Introduction

The Navier–Stokes equations are thought to govern the motion of a fluid in  $\mathbb{R}^3$ , see [1,3]. Let  $\mathbf{u} = \mathbf{u}(\mathbf{x},t) \in \mathbb{R}^3$  be the fluid velocity and let  $p = p(\mathbf{x},t) \in \mathbb{R}$  be the fluid pressure, each dependent on position  $\mathbf{x} \in \mathbb{R}^3$  and time  $t \ge 0$ . I take the externally applied force acting on the fluid to be identically zero. The fluid is assumed to be incompressible with constant viscosity v > 0 and to fill all of  $\mathbb{R}^3$ . The Navier–Stokes equations can then be written as

$$\frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla)\mathbf{u} = \nu \nabla^2 \mathbf{u} - \nabla p, \tag{1}$$

$$\nabla \cdot \mathbf{u} = 0 \tag{2}$$

with initial condition

$$\mathbf{u}(\mathbf{x},0) = \mathbf{u}^{\circ} \tag{3}$$

where  $\mathbf{u}^{\circ} = \mathbf{u}^{\circ}(\mathbf{x}) \in \mathbb{R}^{3}$ . In these equations

$$\nabla = (\frac{\partial}{\partial \mathbf{x}_1}, \frac{\partial}{\partial \mathbf{x}_2}, \frac{\partial}{\partial \mathbf{x}_3}) \tag{4}$$

is the gradient operator and

$$\nabla^2 = \sum_{i=1}^3 \frac{\partial^2}{\partial \mathbf{x}_i^2} \tag{5}$$

is the Laplacian operator. When  $\nu = 0$  equations (1), (2), (3) are called the Euler equations. Solutions of (1), (2), (3) are to be found with

$$\mathbf{u}^{\circ}(\mathbf{x} + e_i) = \mathbf{u}^{\circ}(\mathbf{x}) \tag{6}$$

for  $1 \le i \le 3$  where  $e_i$  is the  $i^{th}$  unit vector in  $\mathbb{R}^3$ . The initial condition  $\mathbf{u}^{\circ}$  is a given  $C^{\infty}$  divergence-free vector field on  $\mathbb{R}^3$ . A solution of (1), (2), (3) is then accepted to be physically reasonable [3] if

$$\mathbf{u}(\mathbf{x} + e_i, t) = \mathbf{u}(\mathbf{x}, t), \quad p(\mathbf{x} + e_i, t) = p(\mathbf{x}, t) \tag{7}$$

on  $\mathbb{R}^3 \times [0, \infty)$  for  $1 \le i \le 3$  and

$$\mathbf{u}, p \in C^{\infty}(\mathbb{R}^3 \times [0, \infty)). \tag{8}$$

## 2. Solution to the Navier-Stokes problem

I provide a proof of the following theorem, see [2,3,5,6].

**Theorem**. Take  $\nu > 0$ . Let  $\mathbf{u}^{\circ}$  be any smooth, divergence-free vector field satisfying (6). Then there exist smooth functions  $\mathbf{u}$ , p on  $\mathbb{R}^3 \times [0, \infty)$  that satisfy (1), (2), (3), (7), (8).

**Proof**. Let **u**, *p* be given by

$$\mathbf{u} = \sum_{\mathbf{L} = -\infty}^{\infty} \mathbf{u}_{\mathbf{L}} e^{ik\mathbf{L} \cdot \mathbf{x}},\tag{9}$$

$$p = \sum_{L=-\infty}^{\infty} p_L e^{ikL \cdot x}$$
 (10)

respectively. Here  $\mathbf{u}_{\mathbf{L}} = \mathbf{u}_{\mathbf{L}}(t) \in \mathbb{C}^3$ ,  $p_{\mathbf{L}} = p_{\mathbf{L}}(t) \in \mathbb{C}$ ,  $\mathbf{i} = \sqrt{-1}$ ,  $k = 2\pi$ , and  $\sum_{\mathbf{L} = -\infty}^{\infty}$  denotes the sum over all  $\mathbf{L} \in \mathbb{Z}^3$ . The initial condition  $\mathbf{u}^{\circ}$  is a Fourier series [2] of which is convergent for all  $\mathbf{x} \in \mathbb{R}^3$ . Equation (1) implies

$$\sum_{\mathbf{L}=-\infty}^{\infty} \frac{\partial \mathbf{u}_{\mathbf{L}}}{\partial t} e^{ik\mathbf{L}\cdot\mathbf{x}} + \sum_{\mathbf{L}=-\infty}^{\infty} \sum_{\mathbf{M}=-\infty}^{\infty} (\mathbf{u}_{\mathbf{L}} \cdot ik\mathbf{M}) \mathbf{u}_{\mathbf{M}} e^{ik(\mathbf{L}+\mathbf{M})\cdot\mathbf{x}}$$

$$= -\sum_{\mathbf{L}=-\infty}^{\infty} vk^{2} |\mathbf{L}|^{2} \mathbf{u}_{\mathbf{L}} e^{ik\mathbf{L}\cdot\mathbf{x}} - \sum_{\mathbf{L}=-\infty}^{\infty} ik\mathbf{L} p_{\mathbf{L}} e^{ik\mathbf{L}\cdot\mathbf{x}}.$$
(11)

Equating like powers of the exponentials in (11) yields

$$\frac{\partial \mathbf{u}_{\mathbf{L}}}{\partial t} + \sum_{\mathbf{M}=-\infty}^{\infty} (\mathbf{u}_{\mathbf{L}-\mathbf{M}} \cdot ik\mathbf{M}) \mathbf{u}_{\mathbf{M}} = -\nu k^2 |\mathbf{L}|^2 \mathbf{u}_{\mathbf{L}} - ik\mathbf{L}p_{\mathbf{L}}$$
(12)

on using the Cauchy product type formula [4]

$$\sum_{l=-\infty}^{\infty} a_l x^l \sum_{m=-\infty}^{\infty} b_m x^m = \sum_{l=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} a_{l-m} b_m x^l.$$
 (13)

Equation (2) implies

$$\sum_{\mathbf{L}=-\infty}^{\infty} ik \mathbf{L} \cdot \mathbf{u}_{\mathbf{L}} e^{ik \mathbf{L} \cdot \mathbf{x}} = 0.$$
 (14)

Equating like powers of the exponentials in (14) yields

$$\mathbf{L} \cdot \mathbf{u}_{\mathbf{L}} = 0. \tag{15}$$

Applying L $\cdot$  to (12) and noting (15) leads to

$$p_{\mathbf{L}} = -\sum_{\mathbf{M} = -\infty}^{\infty} (\mathbf{u}_{\mathbf{L} - \mathbf{M}} \cdot \hat{\mathbf{L}}) (\mathbf{u}_{\mathbf{M}} \cdot \hat{\mathbf{L}})$$
(16)

where  $p_0$  is arbitrary and  $\hat{\mathbf{L}} = \mathbf{L}/|\mathbf{L}|$  is the unit vector in the direction of  $\mathbf{L}$ . Then substituting (16) into (12) gives

$$\frac{\partial \mathbf{u}_{\mathbf{L}}}{\partial t} = -\sum_{\mathbf{M}=-\infty}^{\infty} (\mathbf{u}_{\mathbf{L}-\mathbf{M}} \cdot ik\mathbf{M})\mathbf{u}_{\mathbf{M}} - \nu k^{2}|\mathbf{L}|^{2}\mathbf{u}_{\mathbf{L}} + \sum_{\mathbf{M}=-\infty}^{\infty} ik\mathbf{L}(\mathbf{u}_{\mathbf{L}-\mathbf{M}} \cdot \hat{\mathbf{L}})(\mathbf{u}_{\mathbf{M}} \cdot \hat{\mathbf{L}}) \quad (17)$$

where  $\mathbf{u_0} = \mathbf{u_0}(0)$ . Without loss of generality [2], I take  $\mathbf{u_0} = \mathbf{0}$ . This is due to the Galilean invariance property of solutions to the Navier–Stokes equations. The equations for  $\mathbf{u_L}$  are to be solved for all  $\mathbf{L} \in \mathbb{Z}^3$ . Here we can find a representation of the solution  $\mathbf{u}$ , p and show that  $\mathbf{u}$  can not have a finite time singularity when  $\mathbf{u}^{\circ}(\mathbf{x})$  is smooth.

First note that the solution  $\mathbf{u} = \mathbf{u}(\mathbf{x}, t)$  to

$$\frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla)\mathbf{u} = \mathbf{0},\tag{18}$$

$$\mathbf{u}(\mathbf{x},0) = \mathbf{u}^{\circ}(\mathbf{x}) \tag{19}$$

can be represented by

$$\mathbf{u} = \mathbf{u}^{\circ}(\mathbf{X}),\tag{20}$$

$$\mathbf{X} = \mathbf{x} + t\mathbf{u}^{\circ}(\mathbf{X}). \tag{21}$$

This can be checked as follows via the chain rule.

$$\frac{\partial \mathbf{u}^{\circ}(\mathbf{X})}{\partial t} = \frac{\partial \mathbf{u}^{\circ}(\mathbf{X})}{\partial \mathbf{X}} \frac{\partial \mathbf{X}}{\partial t} 
= \frac{\partial \mathbf{u}^{\circ}(\mathbf{X})}{\partial \mathbf{X}} \mathbf{u}^{\circ}(\mathbf{X}) 
= -\frac{\partial \mathbf{u}^{\circ}(\mathbf{X})}{\partial \mathbf{x}} \mathbf{u}^{\circ}(\mathbf{X}).$$
(22)

Therefore (18), (19) are satisfied. We see here that this  $\mathbf{u}$  satisfying (18), (19) can not have a finite time singularity when  $\mathbf{u}^{\circ}(\mathbf{x})$  is smooth.

The solution  $\mathbf{u} = \mathbf{u}(\mathbf{x}, t)$ ,  $p = p(\mathbf{x}, t)$  to (1), (2), (3), (6), (7) can be represented by

$$\mathbf{u} = \mathbf{u}^{\circ}(\mathbf{X}),\tag{23}$$

$$p = -\nabla_{\mathbf{X}}^{-2} \{ \nabla_{\mathbf{X}} \cdot [(\mathbf{u}^{\circ}(\mathbf{X}) \cdot \nabla_{\mathbf{X}}) \mathbf{u}^{\circ}(\mathbf{X})] \} = P(\mathbf{X}), \tag{24}$$

$$\mathbf{X} = \mathbf{x} + t[\mathbf{u}^{\circ}(\mathbf{X}) - \mathbf{u}^{s}(\mathbf{X})] \tag{25}$$

where  $\mathbf{u}^{s}(\mathbf{X})$  is a representation of the implicit solution  $\mathbf{u}^{\circ}(\mathbf{X})$  to

$$-\frac{\partial \mathbf{u}^{\circ}(\mathbf{X})}{\partial \mathbf{X}}\mathbf{u}^{\circ}(\mathbf{X}) = \nu \nabla_{\mathbf{X}}^{2}\mathbf{u}^{\circ}(\mathbf{X}) + \nabla_{\mathbf{X}}P(\mathbf{X}). \tag{26}$$

In these equations  $\nabla_{\mathbf{X}}$ ,  $\nabla_{\mathbf{X}}^2$ , and  $\nabla_{\mathbf{X}}^{-2}$  denote the gradient, Laplacian, and inverse Laplacian with respect to the variable  $\mathbf{X}$  respectively. Note it is true that

$$\mathbf{u}^{s}(\mathbf{X}) = \frac{1}{\nu} \nabla_{\mathbf{X}}^{-2} \left[ -\frac{\partial \mathbf{u}^{\circ}(\mathbf{X})}{\partial \mathbf{X}} \mathbf{u}^{\circ}(\mathbf{X}) - \nabla_{\mathbf{X}} P(\mathbf{X}) \right]. \tag{27}$$

It is also true that  $\mathbf{u}^{s}(\mathbf{X})$  can be represented by

$$\mathbf{u}^{s}(\mathbf{X}) = -\left(\frac{\partial \mathbf{u}^{\circ}(\mathbf{X})}{\partial \mathbf{X}}\right)^{-1} \left[\nu \nabla_{\mathbf{X}}^{2} \mathbf{u}^{\circ}(\mathbf{X}) + \nabla_{\mathbf{X}} P(\mathbf{X})\right]$$
(28)

in cases where the nonlinearity is not identically equal to zero. The solution can be checked as follows via the chain rule.

$$\frac{\partial \mathbf{u}^{\circ}(\mathbf{X})}{\partial t} = \frac{\partial \mathbf{u}^{\circ}(\mathbf{X})}{\partial \mathbf{X}} \frac{\partial \mathbf{X}}{\partial t} 
= \frac{\partial \mathbf{u}^{\circ}(\mathbf{X})}{\partial \mathbf{X}} [\mathbf{u}^{\circ}(\mathbf{X}) - \mathbf{u}^{s}(\mathbf{X})] 
= \frac{\partial \mathbf{u}^{\circ}(\mathbf{X})}{\partial \mathbf{X}} {\mathbf{u}^{\circ}(\mathbf{X}) - \frac{1}{\nu} \nabla_{\mathbf{X}}^{-2} [-\frac{\partial \mathbf{u}^{\circ}(\mathbf{X})}{\partial \mathbf{X}} \mathbf{u}^{\circ}(\mathbf{X}) - \nabla_{\mathbf{X}} P(\mathbf{X})]} 
\text{or } \frac{\partial \mathbf{u}^{\circ}(\mathbf{X})}{\partial \mathbf{X}} {\mathbf{u}^{\circ}(\mathbf{X}) + (\frac{\partial \mathbf{u}^{\circ}(\mathbf{X})}{\partial \mathbf{X}})^{-1} [\nu \nabla_{\mathbf{X}}^{2} \mathbf{u}^{\circ}(\mathbf{X}) + \nabla_{\mathbf{X}} P(\mathbf{X})]} 
= -\frac{\partial \mathbf{u}^{\circ}(\mathbf{X})}{\partial \mathbf{X}} {\mathbf{u}^{\circ}(\mathbf{X}) - \frac{1}{\nu} \nabla^{-2} [\frac{\partial \mathbf{u}^{\circ}(\mathbf{X})}{\partial \mathbf{X}} \mathbf{u}^{\circ}(\mathbf{X}) + \nabla P(\mathbf{X})]} 
\text{or } -\frac{\partial \mathbf{u}^{\circ}(\mathbf{X})}{\partial \mathbf{x}} {\mathbf{u}^{\circ}(\mathbf{X}) - (\frac{\partial \mathbf{u}^{\circ}(\mathbf{X})}{\partial \mathbf{x}})^{-1} [\nu \nabla^{2} \mathbf{u}^{\circ}(\mathbf{X}) - \nabla P(\mathbf{X})]}.$$
(29)

Therefore (1), (3) are satisfied. We also have

$$p = -\nabla^{-2} \{ \nabla \cdot [(\mathbf{u} \cdot \nabla)\mathbf{u}] \}$$
 (30)

which is obtained by applying  $\nabla \cdot$  to (1) of which ensures (2). Due to the form of the solution we see that **u** can not have a finite time singularity when  $\mathbf{u}^{\circ}(\mathbf{x})$  is smooth. Therefore the theorem is true.

## References

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