We have obtained new evidence for dynamical space by applying correlation analysis to a year of data from a Random Event Generator (REG) device located in Perth, Australia and from another in Muenster, Germany, recorded between July 1, 2012 and June 30, 2013. The results obtained are consistent with results obtained earlier by applying the same analysis to data obtained from a REG located in Manchester UK and the REG in Perth. Consequently evidence for dynamical space is mounting.

For each day we applied correlation analysis to determine travel times for putative waves. Then wave speed and direction, over each 24 hour period, were determined by fitting to the observed travel times, theoretical curves of how travel times would vary with Earth rotation. We thereby derived an average incoming RA, declination and speed for the waves of each day.

A probability density plot of the incoming directions exhibited a peak near \( RA = 4.5 \) h, consistent with previous determinations of incoming 3-space flow direction by Cahill [5] and Dayton Miller [10]. Moreover, removing Earth orbital and gravitational inflow velocities from the observed velocities allowed a peak of higher density to be obtained, which is consistent with predictions of Dynamical 3-Space theory. The peak indicated a most probable average galactic flow direction of \( RA = 4.49^{+0.33}_{-0.19} \) h, \( dec = -80.4^{+0.9}_{-1.4} \) deg, and wave speed of \( 508^{+9}_{-13} \) km/s.

1 Introduction

In Cahill’s theory of Dynamical 3-Space [1, 2], gravity is caused by acceleration of 3-space into matter. The equations governing this process are nonlinear and nonlocal, and predict fractal dynamical 3-space waves.

Random Event Generator (REG) devices commonly generate random numbers by detecting the quantum to classical transition of electrons tunnelling through a barrier in a Zener diode. In the standard interpretation of quantum theory such transitions were assumed to be completely random, however Cahill’s theory and experiments [1] suggest that this is not the case and that the transitions are driven by passage of the predicted 3-space waves. This implies that the numbers output by two spatially separated REG devices may not be 100% independent and that correlation analysis of data from the devices could potentially reveal the travel time of waves that influenced both devices.

To test this possibility we have been analysing data from Global Consciousness Project [7] REG devices. Herein we describe results from a REG located in Perth, Australia and from another in Muenster, Germany, as shown in Table 1 for all days for which data was available, from 1 July 2012 to 30 June 2013.

Of 365 potential days data was available for 198.

<table>
<thead>
<tr>
<th>Table 1: Details of GCP REG Devices Used</th>
</tr>
</thead>
<tbody>
<tr>
<td>Perth</td>
</tr>
<tr>
<td>ID Number</td>
</tr>
<tr>
<td>Latitude</td>
</tr>
<tr>
<td>Longitude</td>
</tr>
<tr>
<td>Device Type</td>
</tr>
</tbody>
</table>
Fig. 1: Travel times from Perth to Muenster from REG-REG data for November 15, 2012. High correlation values for each Muenster-Perth RA hour have been binned and the mean, SD (blue) and SEM (grey) shown. The red curve shows a least square error best fit of a sinusoid to all points. (Horizontal spacing of points is non-uniform because the RA of each point is the mean RA of values in the associated bin).

### 2 Travel times

For each of the 198 days for which data was available, Perth to Muenster travel time $\tau$ values were determined by computing the correlation function,

$$C(\tau, t) = \sum_{t'=-T}^{t+T} S_1[t' - \lfloor \tau/2 \rfloor] S_2[t' + \lceil \tau/2 \rceil] e^{-a(t'-t)^2}$$

for data sequences $S_1[t]$ and $S_2[t]$ containing values output once per second by the REG devices. Here $\lfloor \cdot \rfloor$ and $\lceil \cdot \rceil$ represent floor and ceiling functions that round $\tau/2$ down or up to integer values to ensure correct indexing when $\tau$ is an odd number. $2T = 300s$ is the time interval used about UTC time $t$, and the Gaussian term applies a Gaussian window to suppress end effects. The width of this window is controlled by parameter $a$ chosen as described in the following section.

$\tau$ values were determined by calculating $C(\tau, t)$ for $\tau$ in the range 9 to 23 seconds and then finding which value of $\tau$ in the range 10 to 22 corresponded to the maximum peak value of $C(\tau, t)$.

$\tau$ values with high correlations* were then binned and averaged per RA hour of the Muenster-Perth spatial separation vector that rotates with the Earth. We thereby obtained a mean travel time, Standard Deviation (SD) and Standard Error in the Mean (SEM) for 24 RA directions such as shown in Fig. 1.

### 3 Gaussian window parameter $a$

For Gaussian window parameter $a$ we used a value of 0.0003795 which we had earlier determined as optimum when determining travel times between the REG in Perth and a REG located in Manchester, UK. [3]. As this value also worked well for the Perth-Muenster REG-REG combination, we did not bother to try to determine a better value for Perth-Muenster.

However, for Perth-Manchester we had proceeded as follows.

First, we binned $\tau$ values to obtain histograms such as shown in Fig. 2 and applied the following notion of signal visibility.

*For each day the high correlations were all those higher than a cutoff value which would allow each bin to contain at least one sample. To the bin(s) which then contained only one sample, a second sample with the nearest slightly lower correlation was added to allow calculation of standard deviation.
Fig. 2: Histograms of Perth-Manchester \( \tau \) values detected during different RA hours illustrating a range of signal visibilities from low to high. The multiple peaks are consistent with passage of non-distinguishable waveforms, \( w_n, w_{n+1}, w_{n+2}, \ldots \) etc. three to five seconds apart. Then the correlation of \( w_n \) at one detector with say \( w_{n+1} \) or \( w_{n+2} \) at the other, may be as large as the correlation with \( w_n \). The single peak in the last histogram is consistent with passage of distinguishable waveforms.

Let bar heights \( y_1, y_2 \ldots y_N \) be the frequencies of \( \tau \) values in columns 1, 2 \ldots \( N \). Then we can define signal visibility as mean deviation of bar height over mean bar height, ie.,

\[
V(y) = \frac{1}{N} \sum_{i=1}^{N} \left| y_i - \bar{y} \right| \bar{y}
\]

(2)

Applying this formula to a histogram containing equal numbers of bars with heights equal to \( \text{max} \) and \( \text{min} \) gives,

\[
V = \frac{\text{max} - \text{min}}{\text{max} + \text{min}}
\]

which is the formula for signal visibility used in interferometry. However, whereas the latter has a maximum value of \( V = 1.0 \) when \( \text{min} = 0 \), Eqn. (2) gives higher values when the number of maxima is reduced. Eg if a histogram contains one bar of height equal to \( \text{max} \) and \( (N - 1) \) with height of zero, then for our histograms with 13 bars (2) gives,

\[
V(y) = \frac{2N - 1}{N} \approx 1.85
\]

Using (2) we determined minimum visibility for each day and then the mean minimum for all days for a range of \( a \) values. The blue curve in Fig. 3. shows results obtained from Perth-Manchester data from seven days centered on each full moon during a year. This has a distinct peak at \( a = 0.0003795 \) so we used this value of \( a \) for subsequent calculations.

The red curve shows the mean for all days of the median standard error per day in the hourly \( \tau \) values. This increases with \( a \) because increasing \( a \) reduces the width of the Gaussian window and reduces the number of correlation products that are averaging together, however the rate of increase shows a slight leveling off at peak visibility.
Fig. 3: Plots earlier obtained [3] from Perth-Manchester data of mean minimum signal visibility and mean median travel time standard error for 7 days per each full moon during a year versus Gaussian window parameter $a$. The peak visibility occurs at $a = 0.0003795$.

4 Wave effects in histograms

The histograms of $\tau$ values shown in Fig. 2, earlier obtained for Perth-Manchester travel times, illustrate a range of signal visibilities obtained during different RA hours. Histograms often had multiple peaks consistent with passage of similar waveforms, $\tau_n, \tau_{n+1}, \tau_{n+2}, \ldots$ etc. three to five seconds apart and which may have changed shape during passage from one REG to the other. Then the correlation of $\tau_n$ at one detector with say $\tau_{n+1}$ or $\tau_{n+2}$ at the other, could be as large or larger than correlation with $\tau_n$. The presence of multiple peaks resulted in mean $\tau$ values with large standard deviations and also caused variation of the mean values to be attenuated towards the center of the 10 to 22 second detection range. To compensate for this we applied a disattenuation procedure to derived results as described later.

5 Fitting of sinusoids

Given travel time data for 24 RA directions, the incoming speed and the direction of plane waves can be determined by fitting,

$$\tau = \frac{R \cdot v}{v^2}$$

where $R$ is the REG-REG spatial separation vector and $v$ is the velocity of the Earth relative to the waves. As the daily rotation of $R$ causes the right hand side of Eqn. (3) to be sinusoidal, the fit can be done by fitting a sinusoid to the travel times such as shown in Fig. 1.

The RA of the peak will then indicate the incoming RA of the waves and the amplitude and mean will allow determination of incoming declination and speed. However, the means and amplitudes need to be adjusted to compensate for the above mentioned attenuation effect.

6 Amplitude disattenuation

When $\tau$ values obtained during a given RA hour are averaged together, the presence of multiple peaks in histograms such as seen in Fig. 2 implies that wrong values caused by miscorrelation will be averaged together with correct values and the resultant mean value is then likely to be attenuated towards the center of the detection range. If we assume such wrong values have a random distribution within the observation window, this phenomenon will cause the amplitudes of the sinusoids to be attenuated by an amount equal to $1/(1 + n)$ where $n$ is the average number of miscorrelation values per correct $\tau$ value.
Fig. 4: Disattenuated amplitudes obtained from Perth-Muenster travel times by sorting the original values and then multiplying by a suitable value $m$ to allow the best fit exponential curve to match the range of the detection process. Here use of a logarithmic vertical axis results in a straight line plot.

To compensate for this effect we multiplied the sinusoid amplitudes so that a best fit of an exponential curve to a sorted list of the multiplied values terminated at the amplitude of the largest sinusoid that could be fit to a waveform clipped to the $\tau$ range of 10 to 22. This “largest distinguishable amplitude” is 7.66. The exponential fit is shown in Fig. 4, where a logarithmic vertical axis makes it appear as a straight line plot. This resulted in a multiplier of $m = 3.88 \pm 0.02$.

It can be noted that this value corresponds to $n = (m - 1) \approx 2.9$ miscorrelation values per correct value.

7 Incoming declination and speed

If we let $\tau_{\text{mean}}$ and $\tau_{\text{amp}}$ be the mean and amplitude of each sinusoid fit, $\tau_{\text{mid}}$ be the center of the detection range and $m$ be the disattenuation multiplier determined above, then the disattenuated mean value will be,

$$T_{\text{mean}} = \tau_{\text{mid}} + m(\tau_{\text{mean}} - \tau_{\text{mid}})$$

and the disattenuated amplitude will be $A = m\tau_{\text{amp}}$ and we can define,

$$T_{\text{max}} = T_{\text{mean}} + A$$

$$T_{\text{min}} = T_{\text{mean}} - A$$

Then if $\delta_R$ and $\delta_v$ are respectively the declinations of $R$ and $v$, then $\delta_v$ can be found by numerically solving,

$$\frac{T_{\text{min}}}{T_{\text{max}}} = \frac{\cos(\delta_v + \delta_R)}{\cos(\delta_v - \delta_R)}$$

And wave speed relative to Earth is then,

$$s = \frac{|R|\cos(\delta_v - \delta_R)}{T_{\text{max}}}$$

8 Aberration of incoming wave velocity

Let $v_G$ be the velocity of the Sun relative to distant galactic space, $v_{\text{inS}}$ be velocity due to acceleration of space towards the Sun, $v_{\text{orbit}}$ be the orbital velocity of the Earth and $v_{\text{inE}}$ be velocity due to acceleration
of space towards the Earth. Then the velocity of Earth relative to incoming 3-space can be approximated by,

\[ \mathbf{v} \approx \mathbf{v}_G - \mathbf{v}_{inS} + \mathbf{v}_{orbit} - \mathbf{v}_{inE} \]  \hspace{1cm} (6)

Approximate vector addition of these components is possible because at the Earth’s orbital positions, \( \mathbf{v}_G \), \( \mathbf{v}_{inS} \) and \( \mathbf{v}_{orbit} \) are approximately orthogonal and \( \mathbf{v}_{inE} \) represents a relatively small Earth directed effect that can be modeled as causing a speed increase. (Justification for vector addition of these components can be found in [6].)

From (6) it follows that if 3-space waves have a constant velocity relative to space and if \( \mathbf{v}_{WG} \) is the velocity of the Sun relative to distant waves, then the velocity of Earth relative to incoming waves is,

\[ \mathbf{v}_W \approx \mathbf{v}_{WG} - \mathbf{v}_{inS} + \mathbf{v}_{orbit} - \mathbf{v}_{inE} \]  \hspace{1cm} (7)

which expresses how wave velocities are aberrated by the orbital and inflow velocities. To remove the aberrating velocities and obtain \( \mathbf{v}_{WG} \) from \( \mathbf{v}_W \) we can rearrange (7) as,

\[ \mathbf{v}_{WG} \approx \mathbf{v}_W + \mathbf{v}_{inS} - \mathbf{v}_{orbit} + \mathbf{v}_{inE} \]  \hspace{1cm} (8)

9 Probability density plots of wave direction

Using the methods described above we calculated an incoming RA, declination, speed and associated standard deviations, for each of the 198 days for which data was available.

Fig. 5: Probability density of incoming directions for all days. (\( p/sr \) means probability per steradian and \( h \) is the bandwidth of the Gaussian kernel.)

Fig. 6: Probability density after removing Earth orbital velocity.

Fig. 5 shows a probability density plot of incoming directions for all days with a highest peak near \( RA = 3.0 \, h \) and a lower peak near \( RA = 18 \, h \).

However, if the velocities contributing to the main peak are of physically real waves per dynamical 3-space theory, then they should have been aberrated by Earth orbital and by Earth and Sun inflow velocities and so removing these velocities from the observed wave velocities should result in a higher and more dominant peak.

This turns out to be the case.

Fig. 6 shows that removing Earth orbital velocity results in a more dominant highest peak and Fig. 7 shows that removing the Earth and Sun inflow velocities as well as the Earth orbital velocity results in an even higher and more dominant peak near \( RA = 4.5 \, h \).
By applying a search procedure to find the peak of Fig. 7, the highest probability density was found to be $6.08$ at $RA = 4.49\, h$, $dec = -80.4^0$. Applying a 3D kernel and a search procedure to find highest probability density versus speed for this direction gave the highest density at $508\, km/s$.

We take this direction and speed as our best estimate of $v_{WG}$ that we infer as sun velocity relative to distant galactic waves.

10 Confidence interval estimation

To estimate confidence intervals for the RA and declination of the peak density shown in Fig. 7, we applied bootstrap resampling [8] to the 198 wave directions. To do this we repeatedly made a random selection of 198 directions from the original 198 and then found the peak density for this random set.
Repeatedly applying this procedure gave multiple estimates of RA and declination from which we calculated 68.3% confidence intervals. Fig. 9 shows an example of results obtained from two thousand iterations.

This allowed us to calculate $RA = 4.49^{+0.33}_{-0.19} \, h$ and $dec = -80.4^{+0.9}_{-1.4} \, deg$.

Applying a similar procedure to wave speed for this direction gave $508^{+9}_{-13} \, km/s$.

## 11 RA probability calculation

Having obtained an estimate of $v_{WG}$, we can use Eqn. (7) to predict the most probable values of incoming wave direction and speed $v_W$ that would be observed by Earth based detectors as Earth orbital and Sun inflow velocities vary during a year. The red curve in Fig. 9 shows predicted RA while the points show the RAs of the 198 incoming wave velocities.

![Incoming wave directions (Per-Mue)](image)

**Fig. 9:** Points show the RAs of the 198 incoming wave directions. The red curve shows RA values obtained from Eqn. (7) using our estimate of $v_{WG}$ with $RA = 4.49 \, h$, $dec = -80.4^0$ and $speed = 508 \, km/s$. Of 198 points, 25 lie within $\pm 0.8$ RA hours of this curve. The probability of this degree of closeness arising from chance is $P_{RA} = 0.0017$.

Inspection of Fig. 9 reveals that 25 of the 198 points lie within $\pm 0.8$ RA hours of predicted RA. However if the RAs were random, axial symmetry would imply a uniform distribution and we would expect only $198 \times \frac{16}{24} = 13.2$ points to lie this close to the curve.

We then checked the probability of the observed distribution being due to chance using the formula,

$$P = \sum_{k=r}^{n} \binom{n}{k} p^k (1 - p)^{n-k} \tag{9}$$

where $r = 25$ is the number of points within $\pm 0.8$ RA hours of the curve, $n = 198$ is the total number of points and $p = 1.6/24$ is the probability of a point lying within $\pm 0.8$ RA hours of the curve if the distribution of RAs was random and uniform.

Inserting these figures gives $P_{RA} = 0.0017$.

## 12 Declination probability calculation

Since the derivations of the declinations and RAs are mutually independent, we can validly make an independent check of the probability of the derived declinations. The points in Fig. 10 show the 25 incoming wave directions whose RAs in Fig. 9 were within $\pm 0.8h$ of predicted RA. The blue orbital aberration ellipse shows predicted RA and declination over the course of a year calculated using Eqn. (7) with our estimate of $v_{WG}$.
Fig. 10: Points show the 25 incoming wave directions whose RAs in Fig. 9 are within ±0.8 h of predicted RA. The blue orbital aberration ellipse shows variation of predicted RA and declination during a year due to the combined effect of Earth orbital and Earth and Sun inflow velocities. Of the 25 points, the 20 shown as solid have declinations that lie within ±7.15° of predicted values. The probability of this closeness being a result of chance is $P_{\text{dec}} = 0.00015$.

Of the 24, the 20 shown as solid have declinations that lie within ±7.15° of the predicted values.

This prompts the question, "If the declinations of the points were selected at random from the distribution of declinations that we would have obtained if our data was random, what is the probability that 20 out of 25 would lie this close to their predicted declination?"

To answer this we first calculated empirical declination distribution functions by repeatedly applying our code to randomized travel time values and recording the simulated declinations obtained. Fig. 11 shows the results for $20 \times 365$ declinations (ie we simulated 20 years of data).

Fig. 11: Blue curve shows empirical cumulative distribution function for declinations derived from randomized travel times. That is, for each RA of each day to be simulated, a travel time was selected at random from the set of $24 \times 198$ travel times that had been determined for the 198 days that had complete data.

Then for each of the 20 points, we used the empirical cumulative distribution function to calculate the probability that a declination drawn at random from the distribution would be as close as observed to the predicted value. We then took the maximum probability as a conservative probability for all 20 points. This maximum probability turned out to be 0.4252 and was for a maximum deviation of ±7.1495°.

We could then reapply Eqn. 9 where this time $r = 20$ is the number of points with declinations within ±7.15° of their predicted value, $n = 25$ is the total number of points and $p = 0.4252$ is the maximum
probability of a point having a declination within $\pm 7.15^\circ$ of its predicted value if its declination was drawn at random from the above distribution.

Inserting these figures gives $P_{dec} = 1.50 \times 10^{-4}$.

13 Joint probability

Since the RAs and declinations were independently derived, the joint probability that the closeness of their observed values to their predicted values could have arisen by chance is $P = P_{RA} \times P_{dec} = 0.0017 \times 1.5 \times 10^{-4}$,

which gives,

$$P = 2.49 \times 10^{-7}$$

14 Comparison with related results

Table 2 shows a comparison between values of galactic wave velocity $v_{WG}$ reported in this and earlier papers [3, 4] by this author and a value of galactic space flow velocity $v_G$ reported by Cahill in [5].

<table>
<thead>
<tr>
<th>Ref.</th>
<th>REG separation</th>
<th>RA (hrs)</th>
<th>dec (deg)</th>
<th>speed (km/s)</th>
</tr>
</thead>
<tbody>
<tr>
<td>This paper</td>
<td>Perth-Muenster</td>
<td>$v_{WG}$</td>
<td>$4.49^{+0.33}_{-0.19}$</td>
<td>$-80.4^{+0.9}_{-1.4}$</td>
</tr>
<tr>
<td>Morris [3]</td>
<td>Perth-Manchester</td>
<td>$v_{WG}$</td>
<td>$4.14^{+0.83}_{-0.81}$</td>
<td>$-77.8^{+2.7}_{-2.1}$</td>
</tr>
<tr>
<td>Morris [4]</td>
<td>Perth-Manchester</td>
<td>$v_{WG}$</td>
<td>$4.00 \pm 0.51$</td>
<td>$-79.8 \pm 1.0$</td>
</tr>
<tr>
<td>Cahill [5]</td>
<td>n/a</td>
<td>$v_G$</td>
<td>$4.29$</td>
<td>$-75$</td>
</tr>
</tbody>
</table>

15 Conclusions

In this paper we have presented results that illustrate correlations between widely separated Random Event Generator devices in Perth, Australia and Muenster, Germany that appear to be caused by waves of cosmic origin that are aberrated by Earth orbital and Sun inflow effects, while approaching Earth at some $500 \text{ km/s}$. Our analysis and probability calculations show that it is very unlikely ($P < 2.5 \times 10^{-7}$) that the observed correlations could have occurred as a result of chance alone. In an earlier paper [3] we reported similar results with $P < 5.9 \times 10^{-5}$ after applying identical correlation analysis to data obtained from a REG located in Manchester UK and the REG in Perth.

Consequently evidence for the wave phenomenon seems strong. To interpret and analyse our data we applied Cahill’s theory of dynamical 3-space. This allowed us to obtain intelligible results consistent with the theory and currently seems the best available explanation for what we have observed.

Acknowledgements

Special thanks are owed to GCP [7] and its director Dr. Roger Nelson for enabling access to valuable data from the GCP network of REG devices.

Thanks to Pierre Millette for insightful suggestions with respect to earlier work leading to this paper.
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