# The Center and the Barycenter 

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#### Abstract

In the first part, we deal with the question of which points we have to connect to generate a non self-intersecting polygon. Afterwards, we introduce a polyhole, which is a generalization of a polygon. Roughly speaking a polyhole is a big polygon, where we cut out a finite number of small polygons. In the second part, we present two 'centers', which we call center and barycenter. In the case that both centers coincide, we call these polygons nice. We show that if a polygon has two symmetry axes, it is nice. We yield examples of polygons with a single symmetry axis which are nice and which are not nice. We show that all symmetry axes intersect at one point. In the third part, we introduce the Spieker center and the Point center for polygons. We define beautiful polygons and perfect polygons.


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## 1 Introduction

We look for a criterion to generate a simple polygon.
Let us assume a set of $k+1$ points called Points $\subset \mathbb{R}^{2}$, where Points $=\left\{\left(x_{1}, y_{1}\right),\left(x_{2}, y_{2}\right)\right.$, $\left.\ldots\left(x_{k-1}, y_{k-1}\right),\left(x_{k}, y_{k}\right),\left(x_{k+1}, y_{k+1}\right)\right\}$. We joint the possible edges. We define the subset Union of $\mathbb{R}^{2}$, Union $:=\bigcup\left[\left(x_{i}, y_{i}\right),\left(x_{i+1}, y_{i+1}\right)\right]$ for $i \in\{1,2, \ldots k-1, k\}$. With the expression ' $[a, b]$ ' we mean all points on the line segment between $a$ and $b$ and the boundaries $a$ and $b$. We say that Points is suitable if and only if Union is homeomorphic to the circle $\left\{(x, y) \in \mathbb{R}^{2} \mid x^{2}+y^{2}=1\right\}$.

Definition 1.1. We call Union a polygon if and only if it holds $\left(x_{i}, y_{i}\right) \neq\left(x_{j}, y_{j}\right)$ for $i \neq j$ where $i, j \leq k$. We demand that there are no consecutive collinear points $\left(x_{i}, y_{i}\right),\left(x_{i+1}, y_{i+1}\right)$, $\left(x_{i+2}, y_{i+2}\right)$; also $\left(x_{k-1}, y_{k-1}\right),\left(x_{k}, y_{k}\right),\left(x_{1}, y_{1}\right)$ and $\left(x_{k}, y_{k}\right),\left(x_{1}, y_{1}\right),\left(x_{2}, y_{2}\right)$ are not collinear. The element $\left(x_{i}, y_{i}\right)$ is called a vertex. We name a polygon such that Points is suitable a simple polygon. If we have a simple polygon we include its interior, and it holds $\left(x_{k+1}, y_{k+1}\right)=\left(x_{1}, y_{1}\right)$ and $k>2$.

An $r$-gon is a simple polygon with $r$ vertices.

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## 2 Starlike Polygons

We can start also with a circle $\left\{(x, y) \in \mathbb{R}^{2} \mid x^{2}+y^{2}=1\right\}$. We presume a finite set called $A$ of $k$ different points on the circle, where $k>2$ and $A=\left\{\vec{a}_{1}, \vec{a}_{2}, \ldots \vec{a}_{k-1}, \vec{a}_{k}\right\}$ is in counterclockwise order. We map $A$ bijectively into a set $H=\left\{\vec{h}_{1}, \vec{h}_{2}, \ldots \vec{h}_{k-1}, \vec{h}_{k}\right\}, \vec{a}_{i} \mapsto \vec{h}_{i}$, such that the three points $\vec{h}_{i}, \vec{a}_{i}$ and $(0,0)$ are collinear and the norm of $\vec{h}_{i}$ is positive. We demand that there are no collinear points $\vec{h}_{i}, \vec{h}_{i+1}, \vec{h}_{i+2}$, and also that $\vec{h}_{k-1}, \vec{h}_{k}, \vec{h}_{1}$ and $\vec{h}_{k}, \vec{h}_{1}, \vec{h}_{2}$ are not collinear. We keep the order as in $A$. We move all points with the same vector $\vec{m}$, i.e. $Z:=\left\{\vec{z}_{1}, \vec{z}_{2}, \ldots \vec{z}_{i}\right.$, $\left.\ldots \vec{z}_{k-1}, \vec{z}_{k}\right\} \subset \mathbb{R}^{2}$ where $1 \leq i \leq k$ and $\vec{z}_{i}:=\vec{h}_{i}+\vec{m}$. We keep the order. We call a polygon with a set of vertices $V=\left\{\vec{v}_{1}, \vec{v}_{2}, \ldots \vec{v}_{k-1}, \vec{v}_{k}\right\}$ a starlike polygon if and only if $V$ provided with an appropriate order can be constructed as it is just described for $Z$. We add $\vec{v}_{k+1}:=\vec{v}_{1}$ into $V$. Please see the following Proposition 2.2. Note that $V$ is a suitable set.

Questions 2.1. Is there an alternative description of starlike polygons? Is every convex simple polygon a starlike polygon?

Proposition 2.2. We get a simple polygon $P$ if there is a set of points $V=\left\{\vec{v}_{1}, \vec{v}_{2}, \ldots\right.$ $\left.\vec{v}_{k-1}, \vec{v}_{k}, \vec{v}_{k+1}\right\} \subset \mathbb{R}^{2}$ constructed as above where $k>2$ and
$P:=\bigcap\left\{\right.$ Circle $\subset \mathbb{R}^{2} \mid V \subset$ Circle, where Circle is homeomorphic to the circle area
$\left\{x^{2}+y^{2} \leq 1\right\}$, and the points between $\vec{v}_{i}$ and $\vec{v}_{i+1}, 1 \leq i \leq k$, are a subset of Circle $\}$
Proof. The claim of the proposition is trivial, since $V$ is a suitable set.

It follows that a starlike polygon is a compact set, homeomorphic to any circle area, and for all $1 \leq i \leq k$ the vector $\vec{v}_{i}$ is a boundary point. All starlike polygons are simple polygons.
A triangle is a starlike polygon, too.
Proposition 2.3. If we have a set of $k+1$ points called Points $=\left\{\left(x_{1}, y_{1}\right),\left(x_{2}, y_{2}\right), \ldots\right.$ $\left.\left(x_{k}, y_{k}\right),\left(x_{k+1}, y_{k+1}\right)\right\} \subset \mathbb{R}^{2}$ which forms a polygon we get a simple polygon if and only if Points is suitable.

Proof. Trivial.

## 3 Polyholes

We define a subset of $\mathbb{R}^{2}$, which we will call a polyhole. This geometric structure consists of a finite number of simple polygons $P, P_{1}, P_{2}, P_{3}, \ldots P_{m-1}, P_{m}$. From the polygon $P$ we cut out polygons $P_{1}, P_{2}, P_{3}, \ldots P_{m-1}, P_{m}$.

Definition 3.1. Let $\left\{P, P_{1}, P_{2}, P_{3}, \ldots P_{m-1}, P_{m}\right\}$ be a set of simple polygons. A polyhole is defined as $P$ without $P_{1} \cup P_{2} \cup P_{3} \cup \ldots \cup P_{m-1} \cup P_{m}$

A corresponding definition is possible for polytopes. To define them please see [1].
Definition 3.2. Let $\left\{P, P_{1}, P_{2}, P_{3}, \ldots P_{m-1}, P_{m}\right\}$ be a set of polytopes. A polytopehole is defined as $P$ without $P_{1} \cup P_{2} \cup P_{3} \cup \ldots \cup P_{m-1} \cup P_{m}$.

Questions 3.3. What is the barycenter of a polyhole, if it is realized with homogeneous material of constant thickness? What is the barycenter of a polytopehole of $\mathbb{R}^{3}$, if it is realized with homogeneous material?


Figure 1:
The polyhole on the left-hand side consists of a square where we cut out two triangles.

## 4 Nice Polygons

We assume a suitable set of points called Points $=\left\{\left(x_{i}, y_{i}\right) \mid i \in\{1,2, \ldots k-1, k, k+1\}\right\}$.
We define two 'centers', where the center Cent is just the arithmetic mean of the first and second coordinates of the generating points, respectively.
We got the following formulas for the barycenter $B=\left(B_{x}, B_{y}\right)$ of a simple polygon from [2] or [3]. Please see also [4] and [5]. Area is the area of a simple polygon. Note that Area $\neq 0$ and that in [2] and [4] the barycenter is called a Centroid, and further that $B$ is the center of gravity of the polygon, if it is realized with homogeneous material of constant thickness. Note that the order in the polygon is counterclockwise. We write

$$
\begin{align*}
& D_{i}=x_{i} \cdot y_{i+1}-x_{i+1} \cdot y_{i}, \text { where } 1 \leq i \leq k  \tag{4.1}\\
& \text { Area }=\frac{1}{2} \cdot \sum_{i=1}^{k} D_{i}  \tag{4.2}\\
& B_{x}=\frac{1}{6 \cdot \text { Area }} \cdot \sum_{i=1}^{k}\left(x_{i}+x_{i+1}\right) \cdot D_{i}, \quad B_{y}=\frac{1}{6 \cdot \text { Area }} \cdot \sum_{i=1}^{k}\left(y_{i}+y_{i+1}\right) \cdot D_{i}  \tag{4.3}\\
& \text { Cent }=\frac{1}{k} \cdot\left(\sum_{i=1}^{k} x_{i}, \sum_{i=1}^{k} y_{i}\right) \tag{4.4}
\end{align*}
$$

Definition 4.1. Let us presume a simple polygon $P$. We call $P$ nice if and only if it holds $B=C e n t$.

Proposition 4.2. Every triangle is nice
Remark 4.3. When we use the term symmetry axis of a polygon $P$ we mean a line segment $s$ in the convex hull of $P$ of maximal length, i.e. it holds for a symmetry axis $t$ in the convex hull of $P$ with more than one common point with $s$ that $t \subset s$.

Proposition 4.4. If a simple polygon has two different symmetry axes, it is nice

Proof. The proposition is an easy consequence of the fact that both the center of gravity and Cent must be on a line determined by a symmetry axis. Please see Lemma 4.11.

Lemma 4.5. The property of being nice or being not nice remains with these operations.

- Revolving $P$ by an arbitrary angle around any point
- Shifting $P$ by an arbitrary vector

Proof. We assume $B \neq C$ ent. Let us revolve $P$ by an arbitrary angle around any point. There is a positive distance $d$ between $B$ and Cent. It will be kept since a rotation is a distance preserving map. Hence the distance between the image points of $B$ and Cent is also $d$. After the rotation still $P$ is not nice.
In the case $B=C e n t$ we have nothing to show.
Lemma 4.6. Both operations which we have mentioned above in Lemma 4.5 are distance preserving operations. Therefore the shape of a polygon is kept after these operations.

Proof. Trivial.

In a polygon we fix four real numbers.
Definition 4.7. We define
$\min _{x}:=$ minimum of the set of the first coordinates of the set of the vertices Points of $P$.
$\min _{y}:=$ minimum of the second coordinates of Points,
$\max _{x}:=$ maximum of the first coordinates of Points,
$\max _{y}:=$ maximum of the second coordinates of Points.
Let $\min _{x}<\max _{x}$ and $\min _{y}<\max _{y}$. Note that in a simple polygon $P$ these conditions are fulfilled. We define a simple polygon called $\operatorname{Rectangle}(P)$ by four vertices $\left(\max _{x}, \max _{y}\right)$, $\left(\min _{x}, \max _{y}\right),\left(\min _{x}, \min _{y}\right),\left(\max _{x}, \min _{y}\right)$.

Remark 4.8. In a simple polygon $P$ it holds that both $P$ and the convex hull of Points are in Rectangle $(P)$.
Definition 4.9. Let $s=\{\vec{a}+r \cdot \vec{d} \mid r \in[v, w]$ for fixed real numbers $v, w\}$ be a symmetry axis of a polygon. We define $l(s)$ as the line $\{\vec{a}+r \cdot \vec{d} \mid r \in \mathbb{R}\}$.

Remark 4.10. It holds that $s$ is a subset of $l(s)$.
Lemma 4.11. Let $s$ be a symmetry axis of a simple polygon $P$. Both $B$ and Cent are on the line segment $l(s) \cap \operatorname{Rectangle}(P)$.

Proof. We assume a simple polygon $P$ with a symmetry axis $s$ and centers $B$ and Cent. Note that $B$ is the center of gravity of $P$. Hence $B$ must be on $l(s)$, since $s$ is a symmetry axis of $P$. For the same reason, $B$ is also in $\operatorname{Rectangle}(P)$.
We use Lemma 4.6. We map $P$ by a rotation and a shift parallel the vertical $y$ axis into a second polygon $P^{\prime}$ with a symmetry axis $s^{\prime}$ and centers $B^{\prime}$ and $C e n t^{\prime}$ such that $s^{\prime}$ is on the $x$ axis. Assume a vertex $\left(x^{\prime}, y^{\prime}\right)$ of $P^{\prime}$. Since $s^{\prime}$ is a symmetry axis and it is on the $x$ axis either $y^{\prime}=0$ or there is a second vertex $\left(x^{\prime},-y^{\prime}\right)$ of $P^{\prime}$. If we add all vertices together we get $C e n t^{\prime}=\left(c^{\prime}, 0\right)$ with any real number $c^{\prime}$, i.e. Cent is on the $x$ axis. This means that $C e n t^{\prime}$ is on $l\left(s^{\prime}\right)$. Since $P^{\prime}$ has the same shape as $P$ we get that Cent is on $l(s)$.
It is easy to show that $C e n t$ is a point in $\operatorname{Rectangle}(P)$ : It holds

$$
\begin{equation*}
\min _{x}=\frac{1}{k} \cdot \sum_{i=1}^{k} \min _{x}<\frac{1}{k} \cdot \sum_{i=1}^{k} x_{i}<\frac{1}{k} \cdot \sum_{i=1}^{k} \max _{x}=\max _{x} \tag{4.5}
\end{equation*}
$$

If we consider correspondingly the second coordinate of Cent we get $\min _{y}<\frac{1}{k} \cdot \sum_{i=1}^{k} y_{i}<$ $\max _{y}$, and it follows that Cent is in Rectangle $(P)$.
We get that Cent is in $l(s) \cap \operatorname{Rectangle}(P)$. Lemma 4.11 has been proved.

Two symmetry axes intersect in one point. It is both $B$ and Cent. The proof of Proposition 4.4 is finished.

Corollary 4.12. In a simple polygon with multiple symmetry axes all symmetry axes intersect in one point. It is both $B$ and Cent. It follows that a simple polygon with more than a single symmetry axis is nice.

Note that one symmetry axis is not sufficient, as the kite defined by $(0,0),(1,-1),(3,0),(1,1)$ shows, since $\frac{5}{4} \neq \frac{4}{3}$. It is not nice.

We give an example of a polygon with a single symmetry axis which is nice, but not a triangle.
We present a 5 -gon. It has centers $B=C e n t$, it is about $(0.50,0.85)$. The vertices are

$$
\begin{equation*}
(0,0),(1,0),(1,1),\left(\frac{1}{2}, 1+\frac{1}{2} \cdot \sqrt{6}\right),(0,1) . \text { We get } B=\text { Cent }=\left(\frac{1}{2}, \frac{1}{10} \cdot(6+\sqrt{6})\right) \tag{4.6}
\end{equation*}
$$

This example proves the conjecture that besides triangles only polygons with two or more symmetry axes are nice is wrong.


## 5 Spieker Center and Point Center

In a triangle the Spieker center is well-known. We have gotten the formulas of the Spieker center from [5]. Please see also [6]. The Spieker center of a triangle $A=\left(x_{A}, y_{A}\right), B=\left(x_{B}, y_{B}\right), C=$ $\left(x_{C}, y_{C}\right)$ is its barycenter, at which the triangle is formed by a wire of constant diameter. The interior of the triangle is not regarded. The Spieker center is outside the wire. The sidelengths of the triangle are $l_{1}, l_{2}$ and $l_{3}$, where sides with lengths $l_{1}$ and $l_{3}$ intersect in $A$, while sides with lengths $l_{1}$ and $l_{2}$ intersect in $B$. The coordinates of the Spieker center (spieker ${ }_{x}$, spieker ${ }_{y}$ ) are

$$
\begin{align*}
& \text { spieker }_{x}=\frac{\left(l_{1}+l_{3}\right) \cdot x_{A}+\left(l_{1}+l_{2}\right) \cdot x_{B}+\left(l_{2}+l_{3}\right) \cdot x_{C}}{2 \cdot\left(l_{1}+l_{2}+l_{3}\right)} \text { and }  \tag{5.1}\\
& \text { spieker }_{y}=\frac{\left(l_{1}+l_{3}\right) \cdot y_{A}+\left(l_{1}+l_{2}\right) \cdot y_{B}+\left(l_{2}+l_{3}\right) \cdot y_{C}}{2 \cdot\left(l_{1}+l_{2}+l_{3}\right)} \tag{5.2}
\end{align*}
$$

The concept of the Spieker center can easily be generalized to polygons. We assume the polygon is made from a wire of constant diameter. The shape of the polygon is formed by the wire. We look for its center of gravity; it is generally outside the wire. We consider a new polygon, constructed by $k$ mass centers. Therefore it also has $k$ vertices. We compute the Point center of the new polygon. The Point center of an $r$-gon is defined by the imagination that the masses are in the vertices of the polygon. Let $m_{1}, m_{2}, \ldots m_{r-1}, m_{r}$ be $r$ masses. The polygon has the Point center Point $=\left(\right.$ point $_{x}$, point $\left._{y}\right)$, where

$$
\begin{align*}
& \text { point }_{x}=\frac{1}{M} \cdot \sum_{i=1}^{r} m_{i} \cdot a_{i}  \tag{5.3}\\
& \text { point }_{y}=\frac{1}{M} \cdot \sum_{i=1}^{r} m_{i} \cdot b_{i}, \text { and }  \tag{5.4}\\
& M=\sum_{i=1}^{r} m_{i} \text { is the sum of the masses and }  \tag{5.5}\\
& \left(a_{1}, b_{1}\right),\left(a_{2}, b_{2}\right), \ldots\left(a_{r-1}, b_{r-1}\right),\left(a_{r}, b_{r}\right) \text { are the vertices of the polygon. } \tag{5.6}
\end{align*}
$$

To calculate the Spieker center of a given polygon we have to consider a new polygon, constructed by $k$ mass centers of the $k$ edges. Therefore it also has $k$ vertices. We assume that in the new polygon the masses are on these $k$ vertices. The Spieker center of the given polygon is the Point center of the new polygon. The formulas are

$$
\begin{align*}
& \text { spieker }_{x}=\frac{1}{U} \cdot \sum_{i=1}^{k} l_{i} \cdot\left(\frac{1}{2} \cdot\left(x_{i}+x_{i+1}\right)\right)=\frac{1}{2 \cdot U} \cdot \sum_{i=2}^{k+1}\left(l_{i}+l_{i-1}\right) \cdot x_{i}  \tag{5.7}\\
& \text { spieker }_{y}=\frac{1}{U} \cdot \sum_{i=1}^{k} l_{i} \cdot\left(\frac{1}{2} \cdot\left(y_{i}+y_{i+1}\right)\right)=\frac{1}{2 \cdot U} \cdot \sum_{i=2}^{k+1}\left(l_{i}+l_{i-1}\right) \cdot y_{i}  \tag{5.8}\\
& \text { where } l_{i}=\sqrt{\left(x_{i}-x_{i+1}\right)^{2}+\left(y_{i}-y_{i+1}\right)^{2}} \quad \text { and } \quad U=\sum_{i=1}^{k} l_{i} \tag{5.9}
\end{align*}
$$

We define $l_{k+1}:=l_{1}$. Note the indices in the formulas! Note that it holds $\left(x_{k+1}, y_{k+1}\right)=$ $\left(x_{1}, y_{1}\right)$. The variable ' $l_{i}$ ' means the length of one edge of the polygon. Every edge $l_{i}:=$
$\left[\left(x_{i}, y_{i}\right),\left(x_{i+1}, y_{i+1}\right)\right]$ has a center of gravity $\frac{1}{2} \cdot\left(\left(x_{i}, y_{i}\right)+\left(x_{i+1}, y_{i+1}\right)\right) . U$ is the perimeter of the polygon.
As an example we take the 5 -gon of above. Its Spieker center is about ( $0.50,0.93$ ). In exact coordinates it is

$$
\begin{equation*}
\left(\frac{1}{2}, \frac{1}{6+2 \cdot \sqrt{7}} \cdot\left(2+2 \cdot \sqrt{7}+\frac{1}{2} \cdot \sqrt{42}\right)\right)=\left(\frac{1}{2}, \sqrt{7}-2+\frac{1}{8} \cdot(3 \cdot \sqrt{42}-\sqrt{294})\right) \tag{5.10}
\end{equation*}
$$

Definition 5.1. Let us presume a simple polygon $P$. We call $P$ beautiful if and only if it holds that $B$ equals the Spieker center. We call $P$ perfect if and only if all three centers are the same, i.e. it holds that $B$ equals both Cent and the Spieker center.

Lemma 5.2. Let $s$ be a symmetry axis of a simple polygon $P$. The Spieker center is on $s \cap \operatorname{Rectangle}(P)$.

Proof. The line segment $s$ is a symmetry axis both for the entire polygon and for its contour. Because the Spieker center is the barycenter of the contour it must be on $s$. The statement that the Spieker center is in Rectangle $(P)$ is trivial.

Proposition 5.3. Let a simple polygon has two or more symmetry axes. Then it is perfect.
Proof. The three points $B$, Cent and the Spieker center all are on the line determined by a symmetry axis. There is only a single possibility that all points are on every line.

Conjecture 5.4. A triangle is perfect if and only if it is an equilateral triangle.

The next conjecture contains the previous one.
Conjecture 5.5. An r-gon is perfect if and only if it is an regular r-gon.
Conjecture 5.6. A simple polygon is beautiful if and only if it is perfect. In other words it holds $B=$ Spieker center if and only if $B=$ Spieker center and $B=C$ ent.

Conjecture 5.7. A simple polygon is beautiful if and only if it has more than one symmetry axis.

We end the paper with an infinite number of questions. We define that a connection between two points $A$ and $B$ is a continuous map $f:[0,1] \rightarrow \mathbb{R}^{2}$ such that $f(0)=A$ and $f(1)=B$.

Questions 5.8. We assume a set of $n$ different fixed points in $\mathbb{R}^{2}$. The first set of questions is: Are there connections between all points such that the union of the connections is homeomorphic to a circle? The second is the same, except that only line segments are allowed as connections. In the next questions, we may use a subset of the set of points. We ask whether there are connections of all points such that these connections are homeomorphic to $m$ circles. In the last set of questions, we ask the same, except that only line segments are allowed.

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