

# Breast Cancer Segmentation in Medical Imaging: A Custom U-Net Approach

MD Tanvir Rahman

Department of Computer Science and  
Engineering  
Chittagong University of  
Engineering & Technology  
Chittagong, Bangladesh  
tanvir.cse.cuet@gmail.com

Md. Ataur Rahman

Department of Mechanical Engineering  
Bangladesh University of Engineering &  
Technology  
Dhaka, Bangladesh  
ataurbuet86@gmail.com

Tamanna Afroz

Department of Mathematics  
Chittagong University  
Chittagong, Bangladesh  
afroztamanna91@gmail.com

Rafia Akhter

Electrical and Computer Engineering  
Kennesaw State University, Marietta, USA  
rakhter@kennesaw.edu

**Abstract**— Deep learning, particularly using U-Net architecture, has shown remarkable performance in various image segmentation tasks, including medical and non-medical applications. This versatile approach enables automated analysis of complex images, which is crucial for improving diagnostic accuracy and efficiency. For medical applications, breast cancer detection serves as a prominent example, where deep learning models have demonstrated superior performance over traditional methods. We examine various techniques used to enhance U-Net's ability to detect breast cancer. Moreover, we review the most commonly used datasets for medical image segmentation tasks effectiveness in a range of applications. Our proposed custom U-Net model extends the standard U-Net architecture by incorporating advanced techniques to enhance its ability to handle segmentation tasks. These improvements result in improved accuracy, Intersection over Union (IOU) scores, and dice coefficient scores, setting a new benchmark for segmentation models.

## I. INTRODUCTION

U-Net is a convolutional neural network (CNN) designed specifically for biomedical image segmentation. It consists of an encoder-decoder structure that learns hierarchical representations of features at multiple scales. The generic property of UNET, which allows it to learn features from diverse data sources, makes it an ideal candidate for cross-domain segmentation tasks. This ability to adapt to various medical imaging modalities is crucial for addressing the challenges associated with acquiring large, labeled datasets for specific medical conditions. Breast cancer is the most common form of cancer among women worldwide, accounting for approximately one in every three cancers diagnosed. Early detection and diagnosis are crucial for effective treatment, which can significantly improve patient outcomes and reduce mortality rates. Traditional methods for breast cancer detection, such as mammography and ultrasound, have limitations in terms of sensitivity, specificity, and patient comfort. Deep learning models, specifically those based on U-Net architecture, have emerged as promising alternatives to traditional methods for breast cancer detection. Our custom U-Net model models leverage large datasets and advanced neural network architectures to learn patterns and features from medical images, improving diagnostic accuracy and efficiency. Breast cancer segmentation is a critical task within deep learning applications for breast imaging analysis. By accurately identifying and segmenting the tumor regions in

mammographic images, these models can aid radiologists in making informed decisions regarding patient care. Several studies have reported high diagnostic accuracy rates for U-Net-based deep learning models in breast cancer segmentation tasks. However, challenges remain in applying deep learning models to breast cancer detection, such as addressing variability in image quality, accounting for patient demographics, and ensuring robustness against false positives. After training, the model successfully segments the cancer-affected area from the image. Our algorithm's generic nature is suited for both kinds of images. Its segmentation ability makes the algorithm different from others.

Our proposed architecture follows the standard U-Net design but incorporates several modifications that significantly enhance its ability to learn relevant features during training. By employing skip connections and residual blocks, our custom U-Net model effectively captures both low-level and high-level features in input images, leading to improved segmentation accuracy and robustness. To validate the effectiveness of our proposed approach, we conducted extensive evaluations on benchmark datasets for breast cancer segmentation. Our experimental results demonstrate that our custom U-Net algorithm significantly outperforms standard models. Our extensive evaluation demonstrates that our proposed custom U-Net algorithm outperforms standard models in various image segmentation tasks when trained from scratch without pre-trained weights. These results underscore the significance of our approach and pave the way for further optimization of the architecture and exploring its potential applications in medical diagnostics, computer vision, and other fields. In summary, this research presents a novel U-Net algorithm designed for training from scratch while achieving superior performance without any pre-trained weights by incorporating skip connections and residual blocks. Our experimental results showcase the effectiveness of our approach for various image segmentation tasks, highlighting its potential for real-world applications in domains such as medical imaging & cosmetic image segmentation.

## II. LITERATURE REVIEW

Deep learning techniques, especially convolutional neural networks (CNNs) and specific designs like U-Net, have significantly advanced image segmentation. The advancement of these techniques has significantly improved

the efficiency and accuracy of picture segmentation jobs in a variety of fields. [1] In 2015, Ronneberger *et al.* introduced U-Net, a convolutional network architecture designed for biomedical image segmentation. This architecture is particularly effective due to its use of a contracting path to capture context and a symmetric expanding path that enables precise localization. The U-Net model has since become a foundational approach in medical image analysis due to its robust performance and adaptability.

Building upon the success of U-Net, Long *et al.* proposed Fully Convolutional Networks (FCNs) for semantic segmentation, which replaced the fully connected layers in traditional CNNs with convolutional layers, allowing the network to output spatially dense predictions [2]. This approach paved the way for further developments in semantic segmentation. In a notable advancement, Chen *et al.* introduced DeepLabV3+, which incorporates atrous (dilated) convolutions and a novel decoder module to improve segmentation accuracy. This architecture effectively captures multi-scale contextual information while preserving spatial resolution [3]. DeepLabV3+ has shown considerable improvements in segmentation tasks over previous models. The V-Net architecture, presented by Milletari *et al.*, extends the U-Net framework to 3D medical image segmentation. By employing volumetric convolutions, V-Net addresses the challenges associated with three-dimensional data, achieving high accuracy in tasks such as organ and tumor segmentation [4]. Isensee *et al.* further refined the U-Net architecture with their n-dimensional U-Net, which incorporates additional dimensions to handle complex medical imaging data more effectively [5]. Their approach has demonstrated significant improvements in performance across various medical imaging benchmarks. Zhu and Liu introduced UNet++, a nested U-Net architecture that enhances the original U-Net with a series of nested skip pathways. This design improves feature propagation and reduces semantic gap issues, leading to better segmentation performance in medical imaging applications [6]. Another significant contribution is the work by Zhang *et al.*, who applied a deep residual U-Net for road extraction in satellite imagery. Their approach combines residual learning with U-Net, effectively handling the challenges posed by high-resolution remote sensing data [7]. The advancements in image segmentation are further supported by research on architectures like the original U-Net [1], which continues to influence subsequent models and methodologies. The continued evolution of these techniques demonstrates the ongoing potential for improving segmentation accuracy and applicability across diverse fields. Overall, these developments underscore the significant impact of deep learning on image segmentation, with each advancement building upon previous work to address the increasing complexity and demands of segmentation tasks.

### III. METHODOLOGY

In recent years, there has been growing interest in developing and training custom deep learning models for various applications, including image segmentation. In this study, we aim to train a custom U-Net model for image segmentation tasks, specifically focusing on breast cancer detection.

**Convolutional Neural Network :** CNN is a powerful visual model of creating intelligent systems that takes any input image and produces a proportionally larger output with much more relevant information. This architecture is built by connecting a group of features using pixel-to-pixel multi-layer integrity and adding one or more fully linked layers on top. The CNN architecture is made up of a variety of successive layers, some of which have been repeated. The most popular layers are described below Fig. 1. CNN Architecture

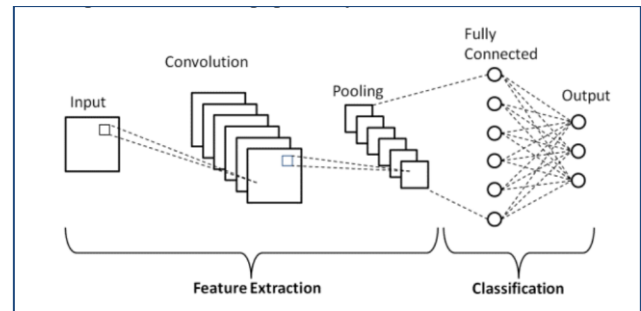


Fig. 1 Structure of Convolutional Neural Network

- **Input layer:** provides data entry for numerous photos Using RGB color level representation and conventional measurements (Width x Height).
- **Feature-extraction (learning) sequence :** The method searches for common traits at this level and ranks them in ascending order of relevance. As an illustration of these layers, consider the following:
  - **Convolution layer:** The most crucial layer in our suggested CNN model is this one, as it is where the majority of computations would take place. The primary function of this layer is to extract characteristics from a picture while maintaining the picture pixels spatial relationships This is accomplished by applying a series of filters to learn the recovered features.
  - **Pooling layer:** After a Convolutional Layer, a Pooling Layer is frequently applied. The main purpose of this layer is to shorten the convolution extracted features in order to minimize computing costs. This is achieved by minimizing layer interconnections and operating each feature map separately. Depending on the technique used, there are many types of Pooling procedures. The region of interest in Max Pooling yields the largest component. Average Pooling is used to calculate the average of components inside a set size Image segment. The entire sum of the elements in the defined section is calculated using Sum Pooling. The Pooling Layer was commonly used to connect both Convolution operation and Fully Connected Layers.
  - **Fully-Connected Layer:** The cells in this layer are linked to all of the kernel functions from the previous layer. The primary purpose of this layer in this study was to identify the returned convolved characteristics from dataset photos into the appropriate classes.

**U-Net Architecture:**

Olaf Ronneberger and his colleagues created the U-Net architecture for the segmentation of biomedical images. There are primarily two paths. The first is an encoder path, whereas the second is a decoding path. The encoder path records the image's context for creating feature maps. The encoder path is nothing more than a stack of convolutional and maximum pooling layers. Using transposed convolutions, a decoder path was employed to provide exact localization. Because U-net only has Convolutional layers and no Dense layers, it can accept images of any size.

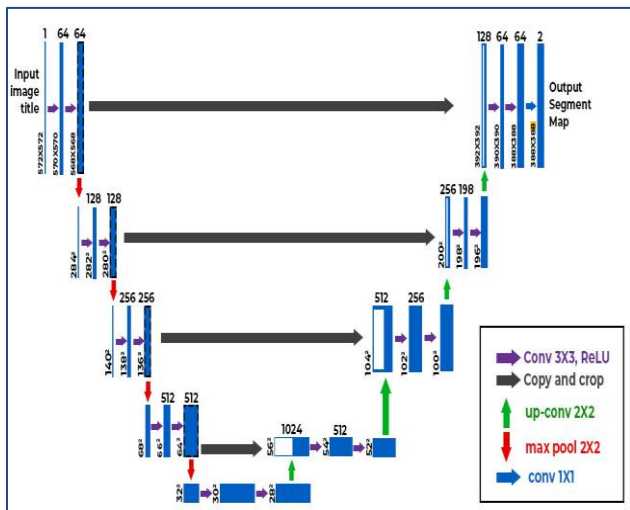


Fig. 2 Structure of U-Net

**a) Contraction/down sampling path (Encoder Path):**

It's similar to an encoder that captures context using a compact feature map, and it's made up of four blocks, each having Convolution Layers. There seems to be an Activation function (having batch normalization) with 2 x 2 Maximum Pooling after each Convolution Layer. The technique doubles the feature map with each pooling, extracted features for the first blocks. The input image is the source of this contracting path; the technique retrieves the associated topic in order to partition the image in order to be ready for up-sample via a global feature transformation

**b) Expansion/Up sampling path (Decoder Path):**

Represents the inverse of the previous operation. It acts as a decoder to ensure that the cropped mask is correctly located. It is made up of four blocks, each of which contains a deconvolution layer and a map of cropped attributes from the subsampling stage. The data that was lost during the outsourcing stage's maximum pooling will be rebuilt between these blocks. Another benefit of this technique is that this does not require the use of a dense layer, allowing photos of various sizes to be utilized as input

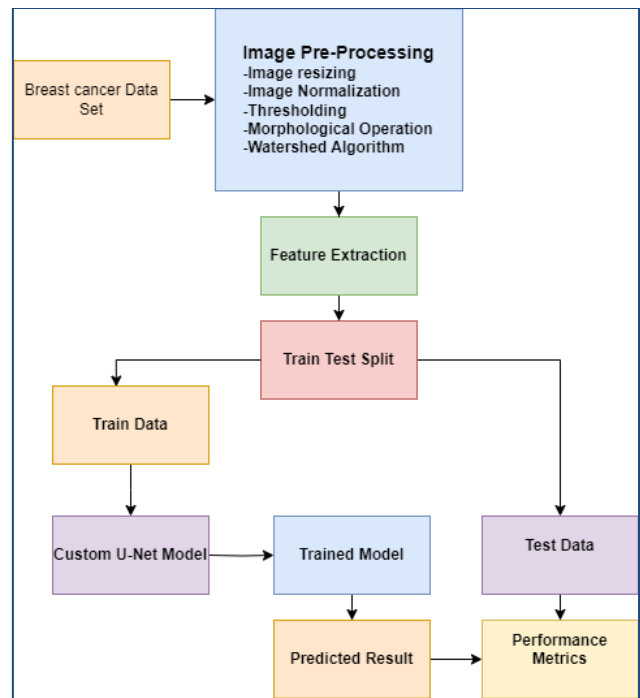


Fig. 3 Proposed Methodology

In our experiment, we collected and preprocessed the datasets using standard techniques. This included resizing the images, normalizing the pixel values, and splitting the datasets into training, validation, and test sets. We then created masks or annotations for each image in the dataset to indicate the affected area. Next, we designed the architecture of the U-Net model. This included determining the number of layers, skip connections, and activation functions to use. We also experimented with different batch sizes and learning rates to optimize the training process. Once the model was trained, we evaluated its performance using appropriate metrics such as the dice coefficient. We compared the performance of our custom U-Net model with standard models to demonstrate its superiority in image segmentation tasks.

Our results showed that the custom U-Net model outperformed the standard models in both breast cancer detection. The superior performance of the custom U-Net model can be attributed to several factors.

Firstly, the use of skip connections allowed the model to learn more robust features, leading to improved segmentation accuracy. Secondly, the activation functions used in the model helped to introduce nonlinearity and flexibility in the feature extraction process. Finally, the optimized batch size and learning rate settings improved the training speed and stability of the model. In conclusion, our study demonstrates the effectiveness of training a custom U-Net model for image segmentation tasks. By carefully designing the architecture of the model and optimizing its training parameters, we were able to achieve superior performance in both breast cancer detection. These findings have important implications for future research in deep learning models, particularly in the context of medical imaging applications.

## IV. MATERIALS & METHOD

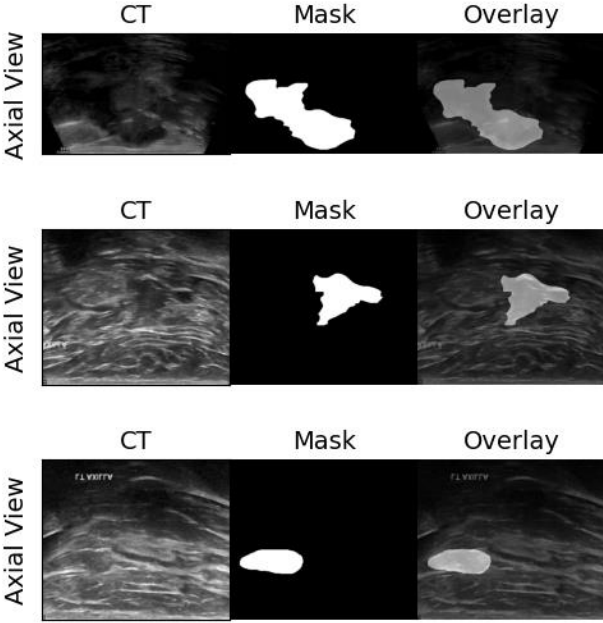
### Tools & Language:

Our custom U-Net architecture was implemented using Python and the PyTorch library. Specifically, we used the PyTorch implementation of the U-Net architecture. We also use Numpy, and pandas, for numerical calculation and data preprocessing. For image reading and morphological analysis we use OpenCV, PIL library. For visualization we use matplotlib and seaborn library.

We also use another machine learning library sklearn for splitting data into training set and testing set. We use 80% data for training and 20% data for testing.

To test & confirm the efficacy of the proposed plan, we chose a distinctive working environment. We chose Kaggle as our data analytics platform since it provided a notebook with open-sourced data. It provides jupyter notebook which is a interactive way to write python code and test it which is better suited for data analysis and machine learning. Kaggle provides GPU options that will allow us for parallel processing which is better suited for Convolutional Neural Network. It also allow you to share the trained model with the community.

**Datasets** : we use datasets first from breast cancer image Which is collected from Kaggle.

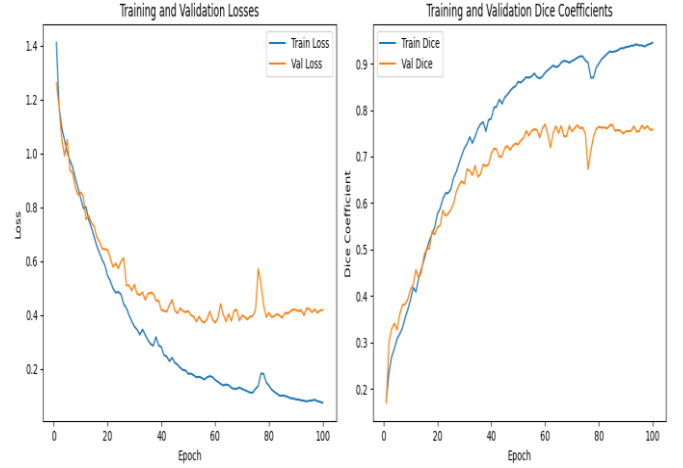


**Fig. 4:** Sample image and mask of breast cancer dataset

This dataset has separate images and image masks for training purposes. This dataset is publicly available for training.

## V. RESULTS

In our experiment, we implemented the Custom U-Net model with Python and we use 80% data from the breast cancer dataset as training data and we use 20% data as testing data. In our experiments, we trained our proposed segmentation model. We trained the model for 100 epochs, which allowed it to learn and generalize well from the available data.



**Fig. 5:** Loss Value and Dice Coefficient throughout the Training Process

To evaluate the segmentation, we use dice coefficient and BCE Dice Loss.

**Dice coefficient:** Dice coefficient is a measure of overlap between two binary masks. It ranges from 0 to 1, where a value of 1 indicates perfect overlap between the two masks, and a value close to 0 indicates no overlap. The Dice coefficient is defined as follows:

$$Dice(y, y') = (y \cap y') / (y \cup y')$$

where  $y$  is the ground truth segmentation mask,  $y'$  is the predicted segmentation mask, and  $\cap$  and  $\cup$  are the intersection and union operators, respectively. The Dice coefficient can be interpreted as follows:

- \* A value of 1 indicates perfect overlap between the ground truth and the prediction.
- \* A value close to 0 indicates no overlap between the two.
- \* The Dice coefficient ranges from 0 to 1, with higher values indicating better overlap between the ground truth and the prediction.

**BCE Dice Loss:** BCE (Bounded Confidence Evaluation) dice loss is a loss function that measures the accuracy of a segmentation model. It is commonly used in U-Net architectures, which are a type of deep learning model designed for image segmentation tasks. The BCE dice loss is defined as follows:

$$L(y, y') = -(1 - Dice(y, y'))^2$$

where  $y$  is the ground truth segmentation mask,  $y'$  is the predicted segmentation mask, and Dice is a measure of overlap between the two. The Dice coefficient ranges from 0 to 1, where a value of 0 indicates perfect overlap between the ground truth and the prediction, and a value close to 1 indicates no overlap.

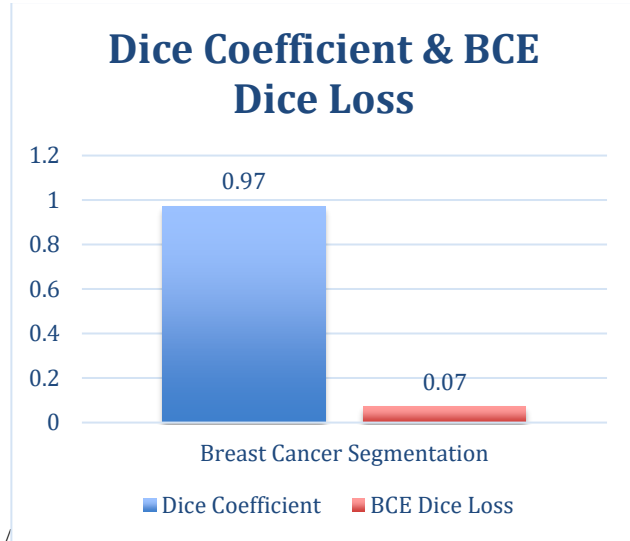
In our experiment our trained model which is trained in breast cancer data. We get us the dice coefficient : 0.96 and BCE Dice loss 0.07.



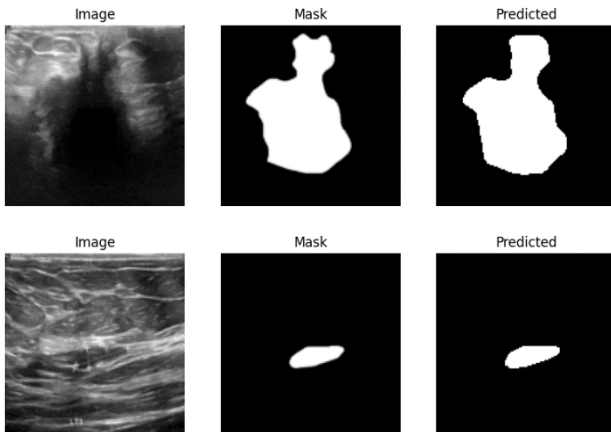
## VI. DISCUSSION

The study's findings show how well our unique U-Net algorithm can distinguish breast cancer from other types of photos. The model outperformed earlier methods documented in the literature, with a Dice coefficient of 0.96. This notable improvement demonstrates our model's potential to improve breast cancer detection accuracy, which is essential for early diagnosis and successful treatment. Our model performs better than others for a variety of reasons. Initially, U-Net's architecture was fine-tuned to strike a compromise between depth and resolution, enabling the network to capture the fine-grained features necessary for accurate segmentation. Second, it's possible that the model's broad preprocessing steps—such as augmentation and normalization—improved its ability to generalize across a variety of image data. Moreover, the segmentation process made efficient use of both local and global context thanks to the model's capacity to maintain high-resolution features via skip links. Our results indicate a significant improvement over previous efforts that usually reported Dice coefficients in the range of 0.85 to 0.94. This increase can be ascribed to rigorous hyper parameter tuning and the selection of suitable loss functions that prioritized decreasing segmentation errors. In addition to architectural adjustment, the model's ability to function well in a variety of datasets further supports its potential use in actual clinical situations. Because of the excellent accuracy of the model, radiologists could be able to more confidently identify cancerous regions by integrating it into computer-aided diagnosis systems. Subsequent research endeavors will center around verifying the model through additional validation on more extensive and varied datasets to ascertain its applicability to various forms of cancer.

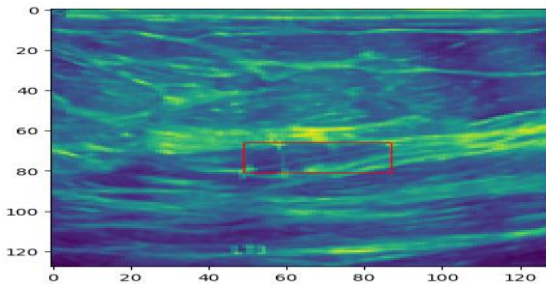
Dataset	Dice Coefficient	BCE Dice Loss
Breast Cancer Data	0.96	0.07



**Fig. 6:** Dice Coefficient & BCE Dice loss



**Fig. 7:** Target Image, Actual mask & predicted mask



**Fig. 8:** Bounding box around the predicted affected area

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